



The Pre-4th Mission Idea Contest UNISEC Global

Rental Satellite for Space Education Development

From KYUSHU INSTITUTE OF TECHNOLOGY



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Introduction



- Trend of Space technology development throughout world
- Situation of Education and Human resource development





EMERGENCE OF NEW SPACE PLAYERS

27 space emerging countries

In 2013

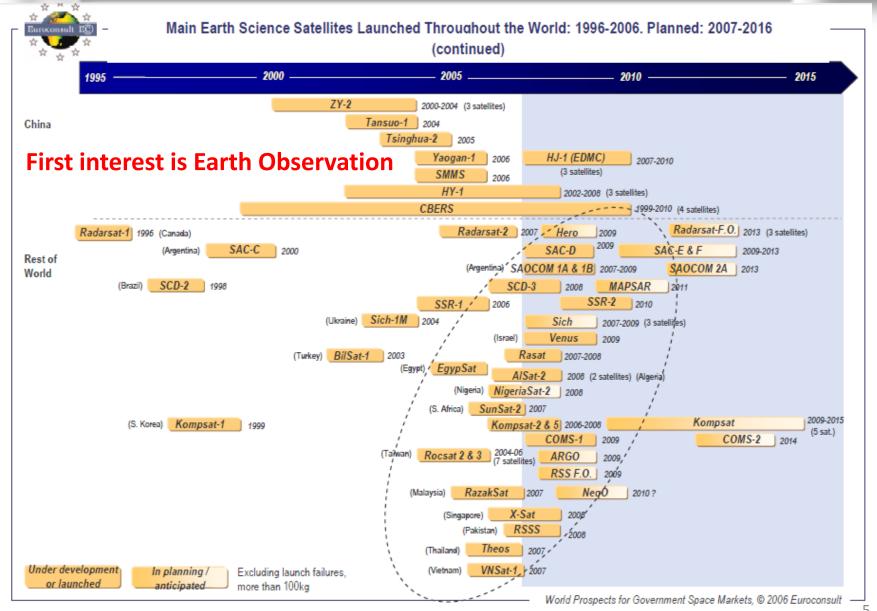
30 satellites Launched

38 satellites have being manufactured

Trends & Prospects for Emerging Space Programs. A Euroconsult Executive Brief | Published August 2013











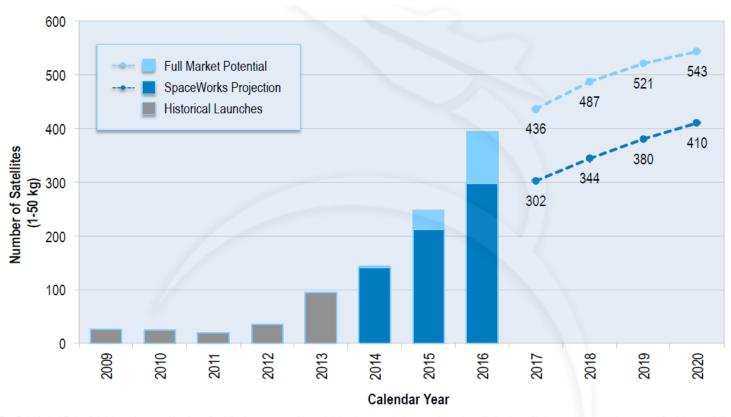
Space Engineering programs approximately 250 universities and institutions 40 countries worldwide

They try to develop their own satellites to provide practical training program





Nano/Microsatellite Launch History and Projection (1 - 50 kg)



The Full Market Potential dataset is a combination of publically announced launch intentions, market research, and qualitative/quantitative assessments to account for future activities and programs. The SpaceWorks Projection dataset reflects SpaceWorks' expert value judgment on the likely market outcome.

Over than 2,000 satellites will require a launch from 2014 to 2020





Issues

Space Debris

More than 500,000 pieces of debris in orbit.

Satellite development and launch cost is too high



Solution



You can control your rented satellite as you want

"Rental Satellite"



Benefits



- To provide sustainable "real" practical training for Space Engineering courses syllabus
- To contribute to decrease Space debris
- Low-cost and fast usage of satellite for users
- To increase collaboration between Space developed country and Space emerging countries



Mission Objectives

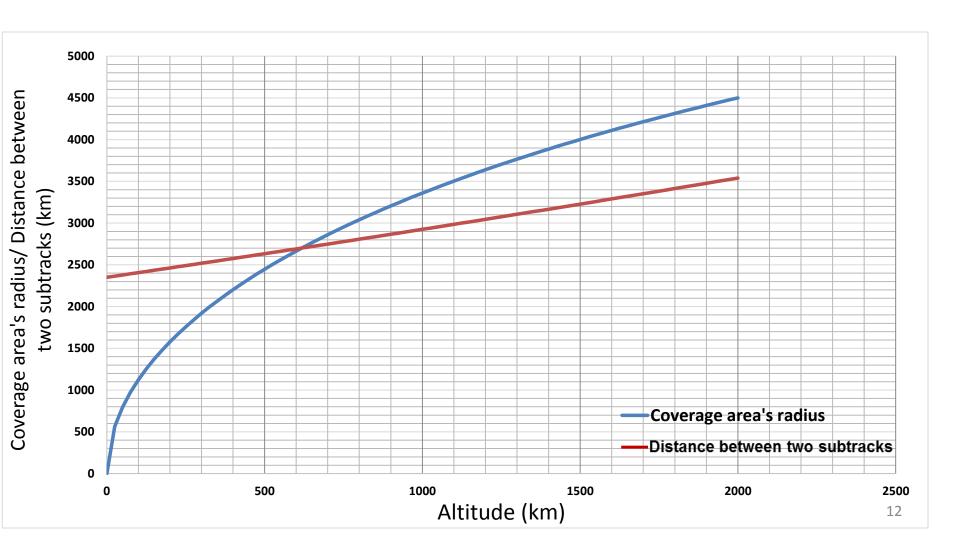


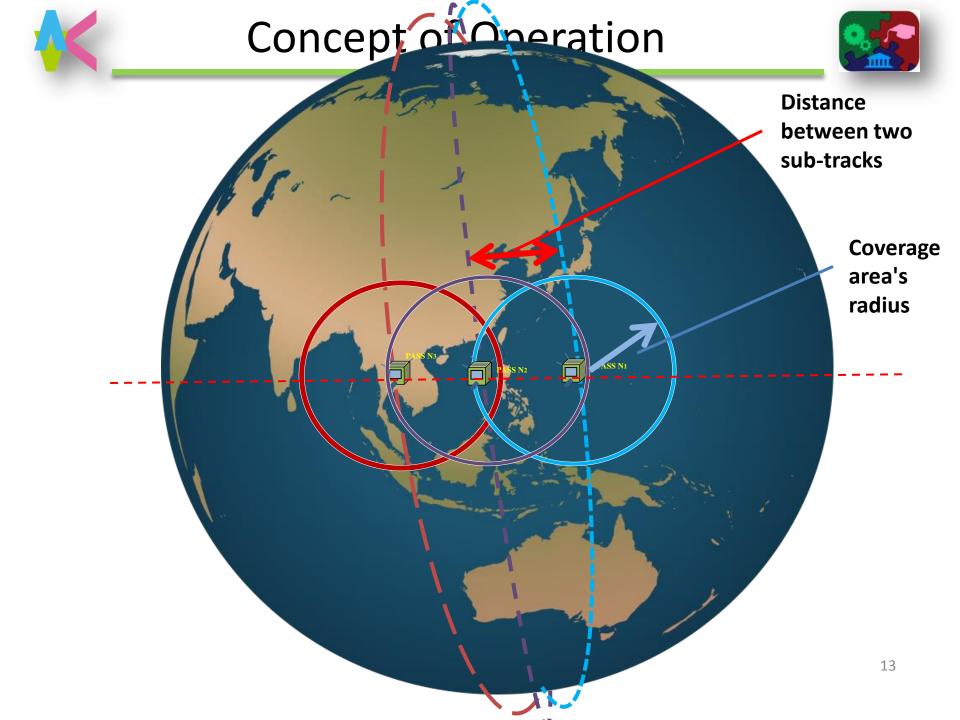
- 1. Provide atmospheric measurement data.
- 2. Provide Earth observation data to the end users.
- 3. Provide users opportunity to communicate with the satellite at least 4 times per day.
- 4. Demonstration of Attitude Determination and Control System.
- 5. Users can test their algorithm checking in orbit





- Orbit is sun-synchronous orbit with inclination of 98 degrees.
- Altitude is above 625 km.









Total communication time per day (minutes)

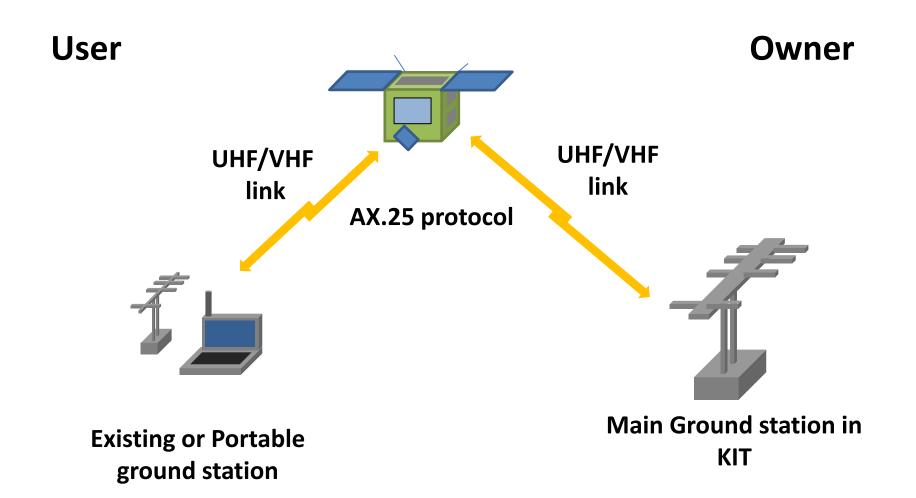
Altitude (km)

	400	500	600	700	800	900	1000
90	154.3	166.9	186.3	205.3	217.1	225.5	241.8
80	140.3	157.4	176.3	196.6	211.1	218.0	234.9
70	104.5	117.6	134.0	156.3	177.3	189.0	209.1
60	66.6	90.3	106.3	123.4	144.2	147.7	162.5
50	48.1	60.9	69.8	83.6	95.4	101.6	120.1
40	36.8	42.5	52.6	65.5	73.5	79.5	90.5
30	35.2	40.5	49.2	56.5	59.2	61.0	70.0
20	32.8	37.6	45.1	49.0	55.1	59.7	66.4
10	28.8	33.1	40.2	48.3	54.0	58.3	66.7
0	24.3	26.5	39.9	47.4	52.8	56.7	67.1
-10	21.3	26.8	39.2	46.5	52.9	60.6	68.2
-20	24.0	34.9	44.6	52.9	58.5	71.1	76.7
-30	31.5	39.4	47.5	55.6	69.3	77.0	81.7
-40	35.9	42.2	54.1	66.7	75.3	82.0	91.4
-50	42.5	56.7	69.9	0.08	95.0	105.6	114.5
-60	66.5	87.7	104.8	117.9	128.5	140.6	151.9
-70	98.7	114.2	133.8	144.7	165.6	188.9	194.9
-80	131.6	154.9	176.0	183.7	201.1	217.9	218.5
-90	144.6	166.2	186.3	191.7	208.8	225.5	226.1



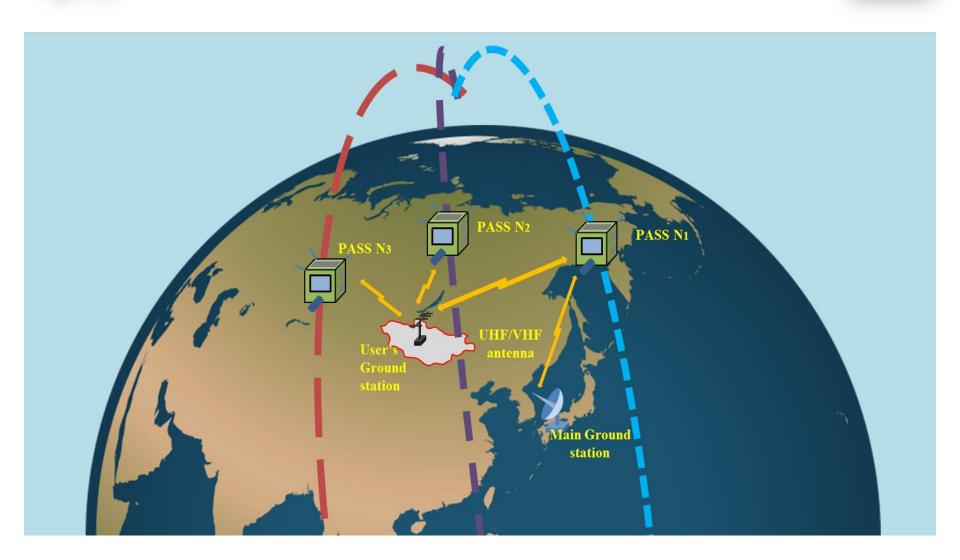


GROUND SEGMENTS



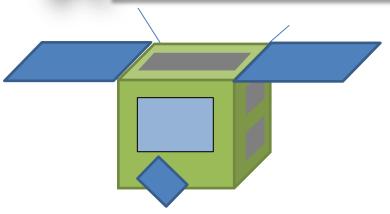












Structure

- Deployable Solar paddles
- Size < 30x30x30cm

Payload:

- Low Resolution Camera
- Atmospheric sensors

SPACE SEGMENT

Satellite's Mass and Power budget

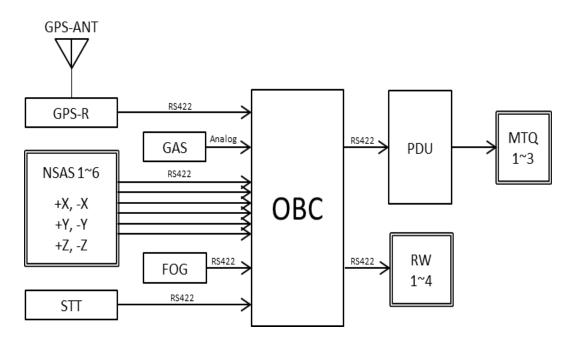
Subsystem	Mass(Kg)	Power(W)
Payload	1	2
ADCS	2.5	5
EPS	2	-
C&DH	0.5	1
СОМ	1.5	0.5
Thermal	0.5	-
STR	5	-
Sum	13	8.5
Margin	2	1
Total	15	9.5



Key Performance Parameters



Attitude Determination and Control System



ADCS Block Diagram

Sensors:

NSAS (Non-spin Solar Aspect Sensor) GAS (Geomagnetic Attitude Sensor) STT (Star Tracker) FOG (Fiber Optical Gyroscope) GPS

Actuators:

RW (Reaction Wheel)
MTQ (Magnetic Torquer)



Key Performance Parameters



Possibility of Users

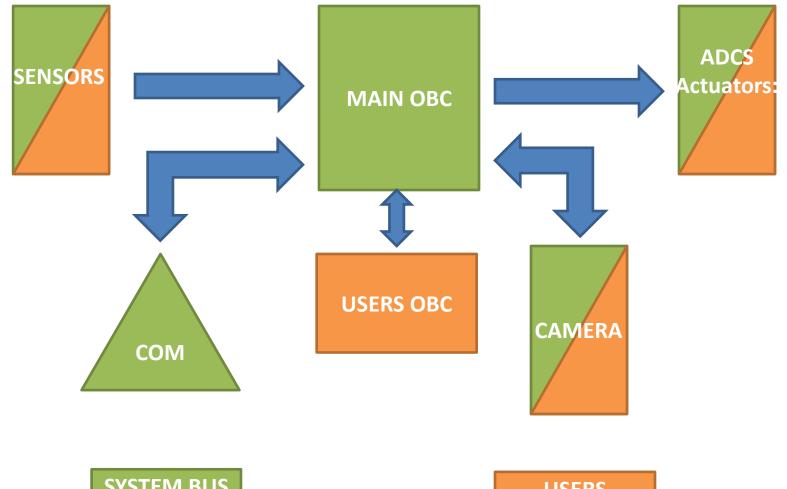
- To control satellite and take atmospheric data (Level 1)
- To capture images by low resolution camera (Level 1)
- Algorithm checking (Level 2)
 - OBC algorithm,
 - Camera algorithm
 - ADCS algorithm



Key Performance Parameters



Block diagram of internal sub systems



SYSTEM BUS

USERS



Implementation



Estimation of total life cycle cost [6]

<satellite cost=""></satellite>	Specifications	Cost (M\$)
1.1 Bus Cost	Low level bus <20 kg, Size 30x30x30 (mm)	0.3
2.1 Dayland Cost	Low resolution (GSD 50m), 200 x 200km	0.1
2.1 Payload Cost	Atmospheric Sensors	0.1
<ground cost="" station=""></ground>		
2.1 Cround station development	Amateur Very High Frequency (145 MHz) and	0.05
3.1. Ground station development	Ultra High Frequency (435 MHz)	0.05
3.2 Operation Cost (On the main Ground	Engineers and Maintains	0.1
station and Rentals Ground stations)	Engineers and ivialitatis	U.1
3.3 Management Cost (per one mission,	Prepare to operation on users ground stations	0.1
for one time)	repare to operation on users ground stations	0.1
<launch cost=""></launch>		
4.2 Single satellite launch as a piggyback	The satellite launch cost to coordinated orbits	1
satellite	The satellite faulth cost to coordinated orbits	1
Total Cost		1.75



Implementation



Estimated revenue and benefit

	Initial investme nt (USD)	Users payment per 1 month (USD)	Estimated total revenue for 60 months (USD)	Profit for 60 months (after 60 months all revenue becomes profit)(USD)				
Built and operation	750000	15000	900000	150000				
Launch	1000000	20000	1200000	200000				
Total	1750000	35000	2100000	350000				



Implementation



	Month	Month	Month	Month	M onth	Month	Month 7	Month	Month	M onth	Month	Month 12	Month 13	Month 14	M onth	Month 16	Month 17	Month 18	
	BBM				E	M	<u> </u>				**	14	FM	.,	10	10		Launch	
▲ PDR start of Month 1 ▲ ICR start of Month 3								△ CDF	start of	Month 9							start Ionth 17		

BBM (bread board model) Phase tasks

Until PDR ()

- Sub-systems design
- Sub-systems development separately
- PDR objectives demonstrate feasibility using hardware (Testing, analyses, etc...)
- STM Development and testing

PDR to ICR

- Risk management 1
- Bus sub-systems integration
- Missions integration
- Table-sat 1: Bus+ missions universal board integration and testing
- ICR objectivesdemonstrate interfaces are working properly, validate design to move to EM

EM (Engineering model) Phase tasks

Until CDR

- Sub-systems EM design
- Integration with other sub-systems
- EM structure development
- EM thermal model development
- EM environment testing
- EM assembly, integration, and testing (EM AIT)
- Table-sat 2
- Risk management 2
- Safety Review 1&2

CDR Objectives

- Demonstrate satellite workability as a whole
- Validate detailed design and interfaces

FM (flight model) Phase tasks Until FRR

- Manufacture of FM parts
- Integration FM subsystems
- FM structure development
- FM thermal model development
- FM environment testing
- FM assembly, integration, and testing (FM AIT)
- End to end operation testing
- Risk management 3
- Safety Review 3

FRR Objectives

- Demonstrate satellite is safe to fly as piggy-back
- Demonstrate satellite proper workability
- Demonstrate satellite is ready to be delivered



Expected (Possible) Results



We have estimated 5 years (60 months) life time of operation in orbit, and during this time expected results as below:

- Minimum success: The satellite can provide the opportunity for at least 5 countries or institutions without a dedicated satellite to download data.
- Full success: The satellite can provide the opportunity for users in every country in the world
- Extra success: The satellite can provide the opportunity for users in every country to obtain data, control the satellite and further some companies would pay money to use this service for more than 5 years.





Thank you!

