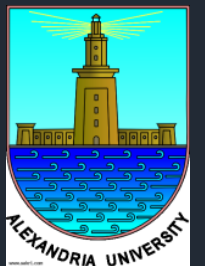


UNISON-Egypt

A Further Step toward Space
Education and Understanding

Ahmed Abd El-Moniem

Senior Student at Aerospace Engineering
Department, Cairo University



UNISON Egypt - SSTLab



- Space Systems Technology Laboratory (SSTLab) is a student based organization at Aerospace Engineering Department, Cairo University, which was established in August 2011. SSTLab has become the main contact point of UNISON Egypt.
- UNISON Egypt includes laboratories from different universities: Cairo, Alexandria , MSA and Zewail.





UNISON Egypt Activities 2016

- UNISON Egypt has supported many projects:
 - CanSat Training Program (CTP)
 - Rover Back
 - Quad Copter
 - Cube Satellite Systems



CanSat Training Program (CTP)

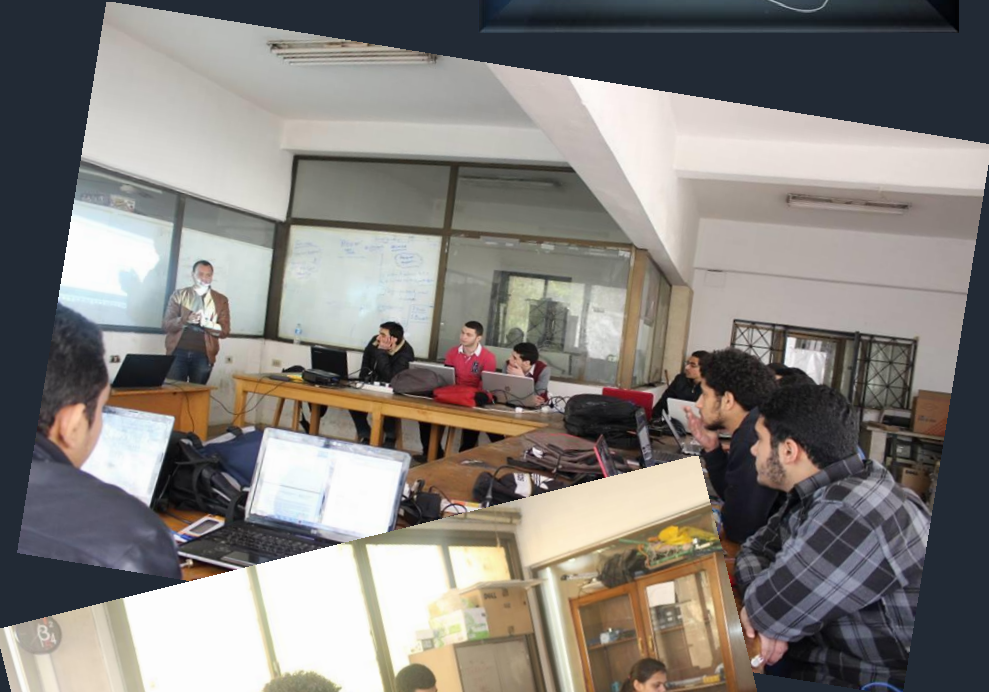
- SSTLab continues the CTP series which started in 2010, by organizing CTP6 in Cairo university venue.





CanSat Training Program (CTP6)

- SSTLab has successfully trained 20 students this year from Cairo and Alexandria universities. The training was held in mid-year vacation, from January 31, 2016 to February 11, 2016.
- UNISON Egypt has organized a national competition among trainees and nominates the winner to participate the following ARLISS CanSat competition.

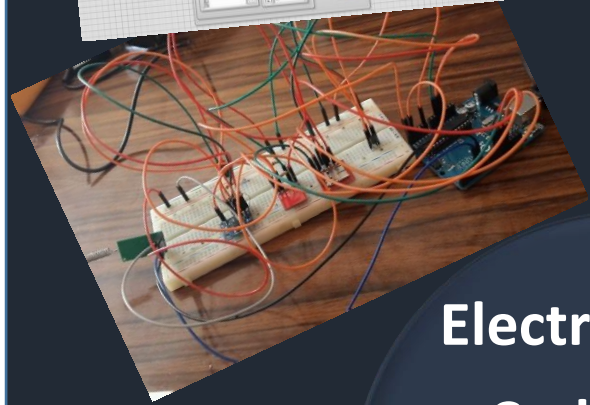
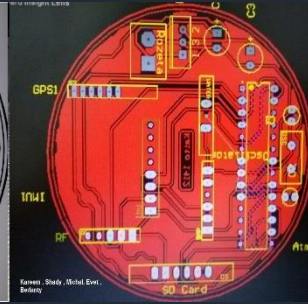
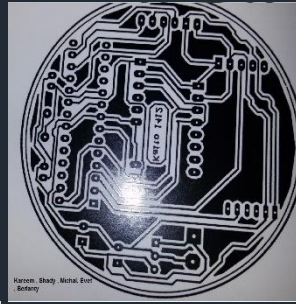




MSA CanSat Training Program (MSAT)

- UNISON Egypt Chapter in MSA university has started its CanSat training this year by training 40 students.





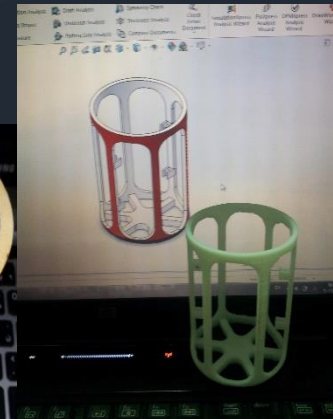
Electrical

- Code
- PCB
- Ground Station

CanSat Subsystem

Mechanical

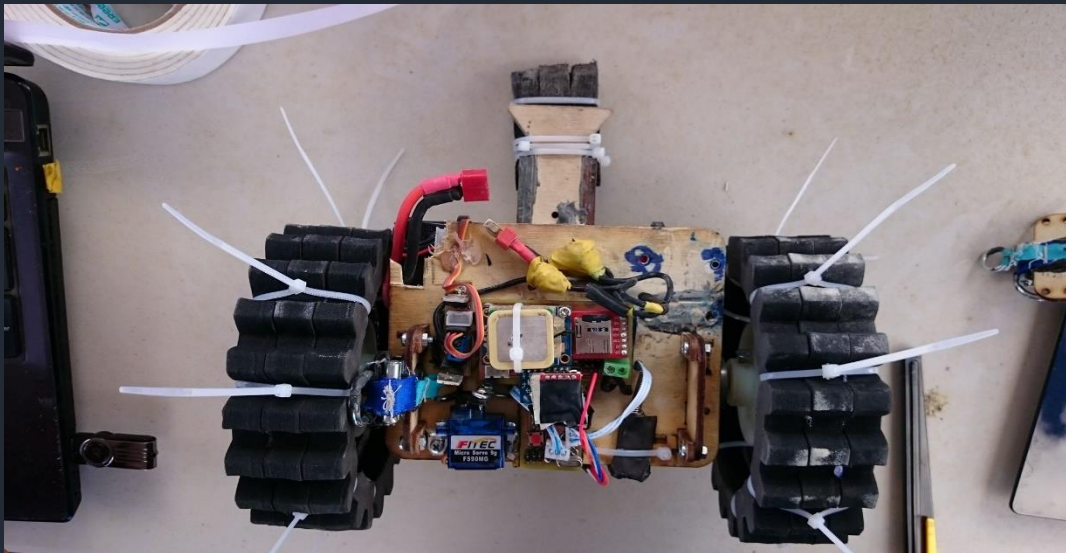
- Recovery System
- Structure





Rover Back

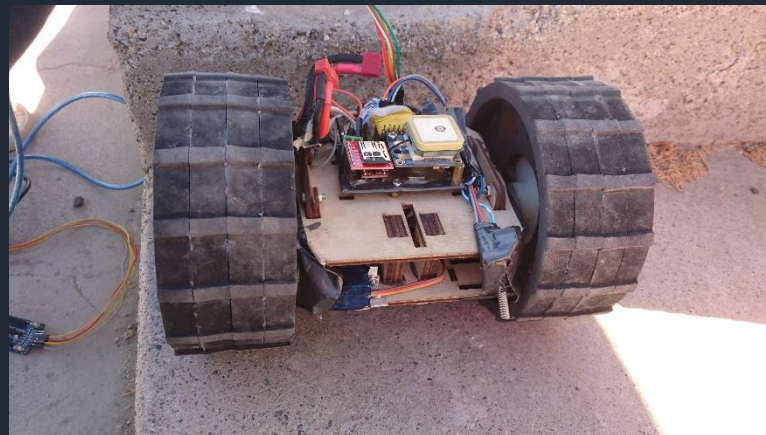
- SSTLab starts again the rover back full program after last two years of participation in ARLISS competition years (2014 and 2015).
- The Lab holds “Rover Back” training program including three major sub-teams: mechanical, recovery and control (electronics) teams.



Rover Back



- SSTL Rover Back participated ARLISS competition 2016, held from 11 to 16 September and came in 7th place. Adding some improved subsystems such as Dual Deployment recovery mechanism and a mode of complex control action which works when the rover stuck in sand.



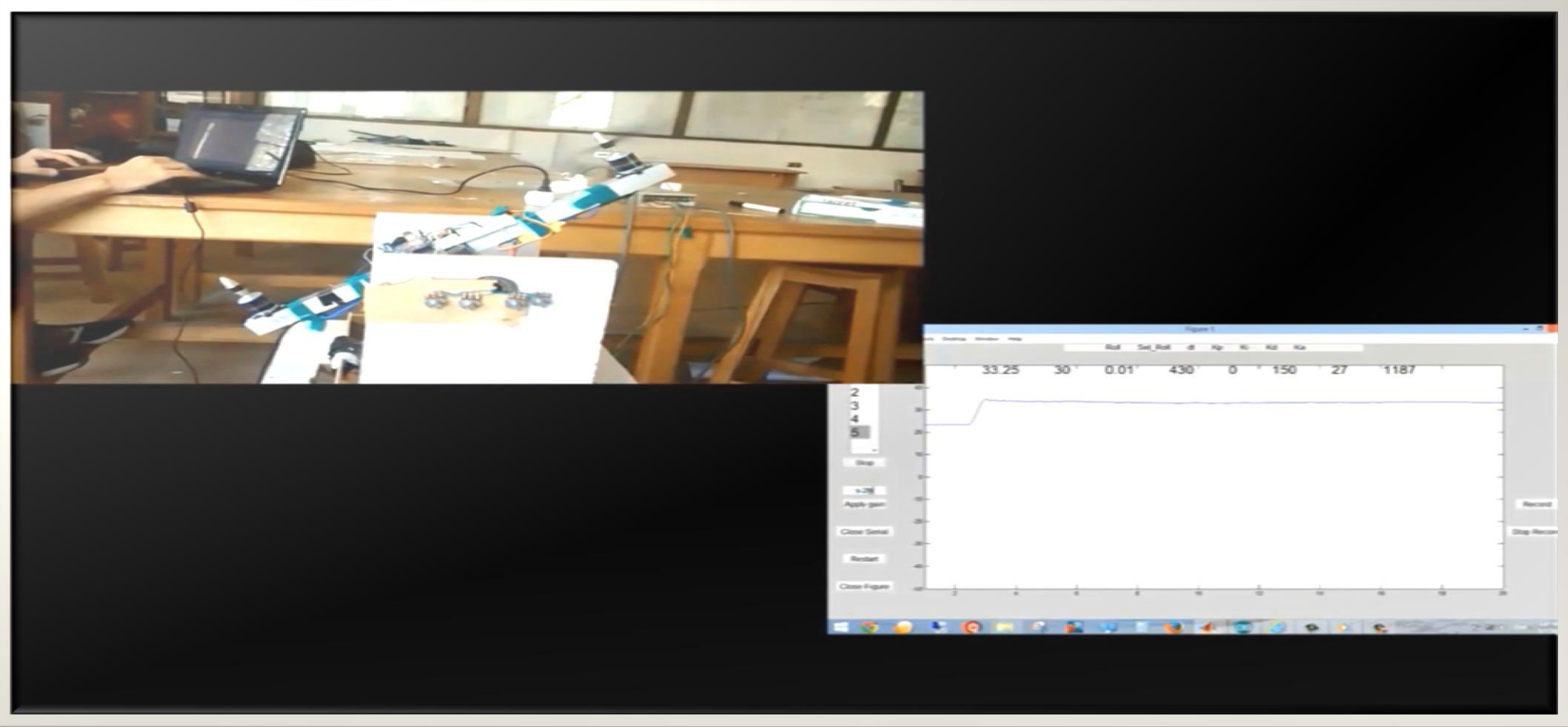


Quad-Copter

- SSTLab's targets of quad-copter for this year are
 - Attitude and altitude control.
 - Achieving good performance in position control that enables us to use in several applications.
 - Getting suitable identification for the model using system identification.



Quad Copter





Quad Copter

- SSTLab Quad-Copter won the “The Best mechanical Engineering Project” in Egyptian Engineering Day (EED), September 2016.
- Future Work
 - Trajectory generation.
 - Obstacle avoidance.
 - Tracking of objects.
 - High altitude flight.



Cube Satellite Systems

- CubeSat project which started with the first early prototype in 2008, followed by the second one in 2013 and third one in 2014. Last year a group of undergraduate students started the fourth development cycle.



- This year they are working on the Laser communication and ADC subsystems as a graduation project.



Future of UNISON- Egypt

- Making much of students' actions and creative ideas unbounded by traditional ones, which will lead to breakthrough in space technology.
- Continuing in space applications and projects like CanSat, CubeSat, Rover, Quad-copter and Rocket to get the “Know-how” knowledge and practical experience in space technology.
- Starting to develop a true space product and try to launch it in space like our University-Sat 1.
- Enhancing UNISON – Egypt to include more Egyptian universities.



Thank You

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