

CanSat & Rocket Experiment('99~)



Hodoyoshi-1 '14



# CanSat and CubeSat History in Japan - How they started and contributed to education and technologies

Shinichi Nakasuka  
University of Tokyo



CubeSat 03,05



PRISM '09



Nano-JASMINE (TBD)

# Japanese Recent History of University Micro/Nano Satellite Activities

Follow-on projects by many universities

2003.6 Launch

UNISEC

*CubeSat(2000-)*: Real Pico-satellite to be launched to orbit



2001

2000

*CanSat (1999-)*: Sub-orbital(4km) experiment of quasi-real satellites. Real operation



1999

1998

*USSS (University Space Systems Symposium: 1998-)*  
Real satellite projects formed by Japan-US students

1993

*Satellite Design Contest (1993-)*: 1st step paper work training





# USSS 1998 ~ 2005

## University Space Systems Symposium

US-JAPAN University discussion workshop  
to create real space projects in Hawaii



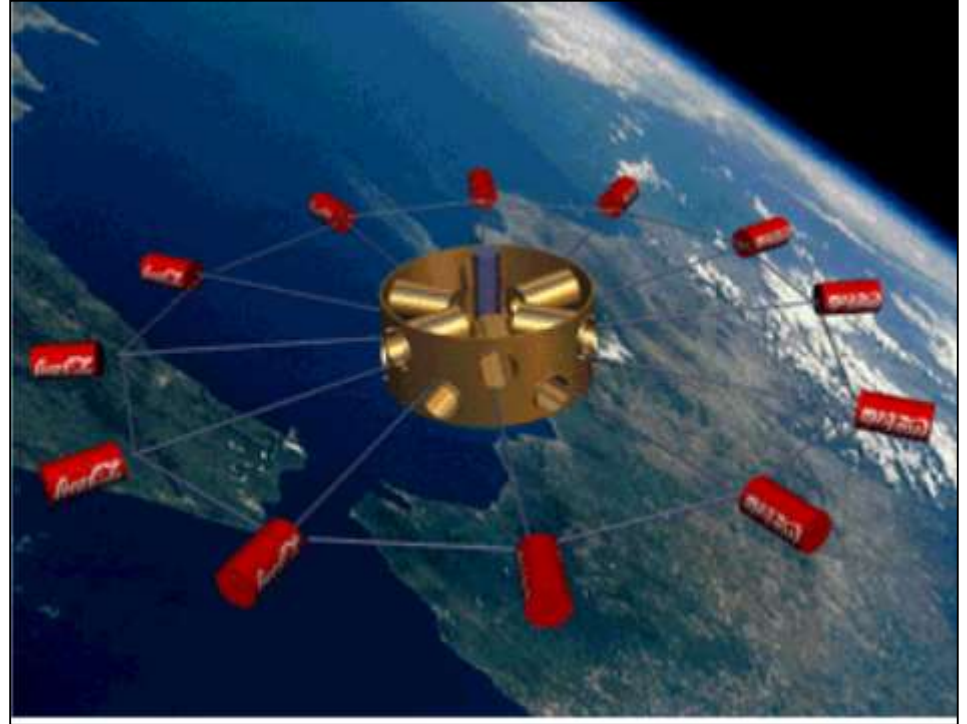


# USSS has been held annually in many islands under JUSTSAP

1998	Oahu	CanSat proposed
1999	Kauai	CubeSat proposed
2000	Big Island, Hiro	
2001	Big Island, Kona	
2002	Oahu	
2003	Oahu	
2004	Oahu	
2005	Oahu	



# Birth of CanSat at 1<sup>st</sup> USSS 1998



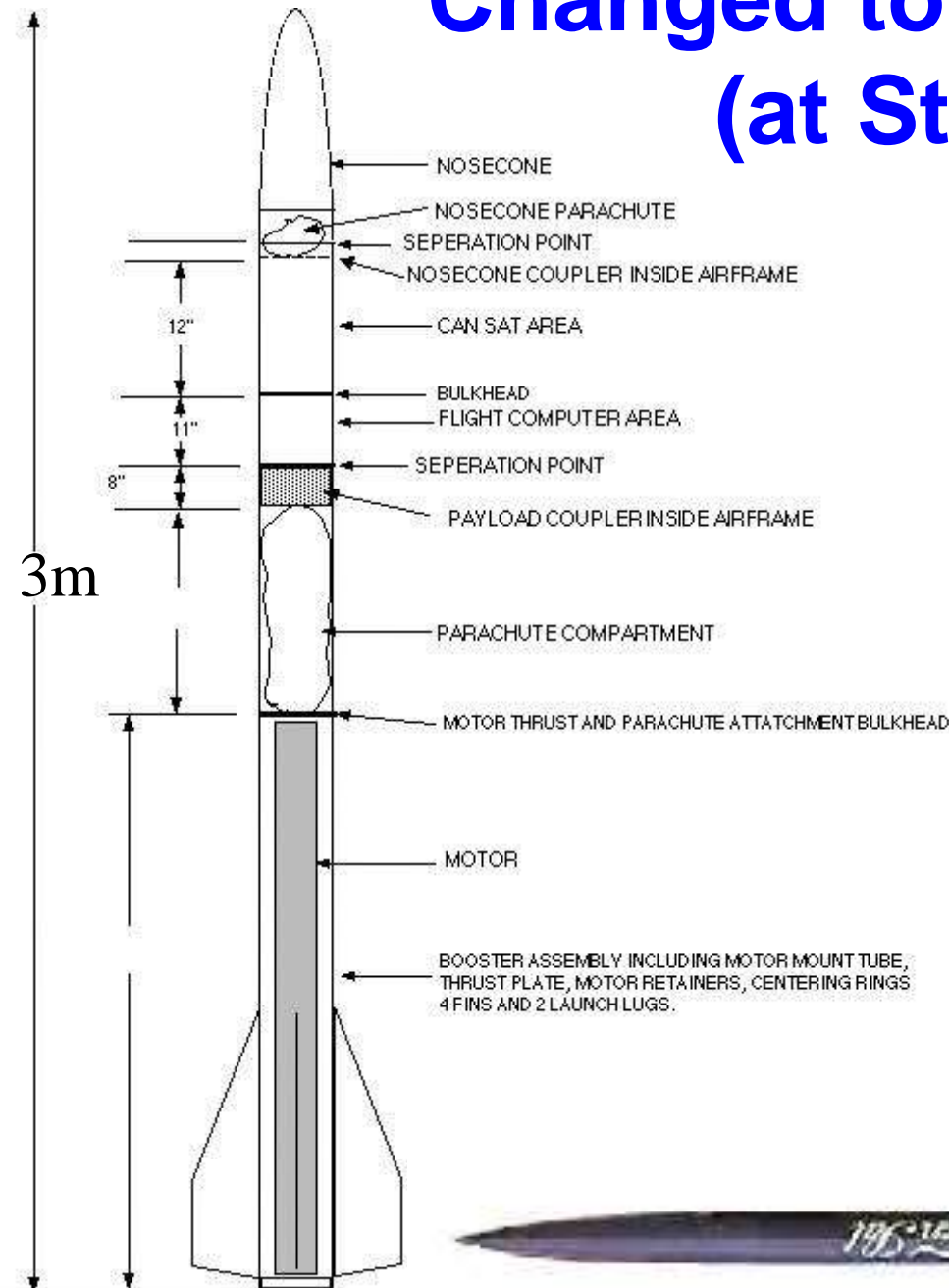
Initial Concept: launch all the CanSats and operate them in next USSS (one year later)

“Let’s make a satellite out of this Coke-can !!”

*Prof. Bob Twiggs, Stanford University*



# Changed to Suborbital Launch (at Stanford, April 1999)

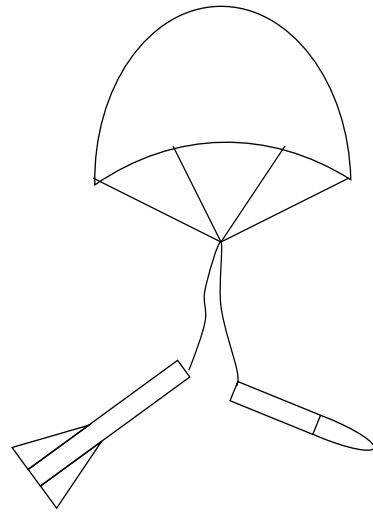


- AEROPAC Amateur Rocket group
- Lift 1.8 kg to 12000ft
- Three 350ml sized cans or one “Large sized can (open class)”
- One flight cost: \$400
- at Black Rock Playa (Nevada, USA)

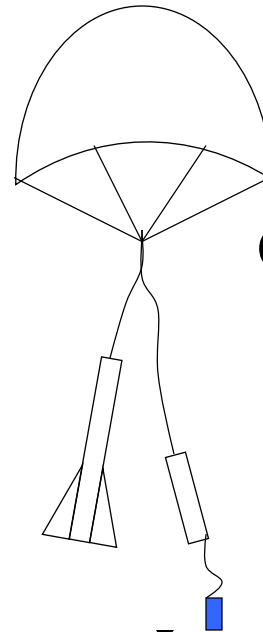


**ARLISS**

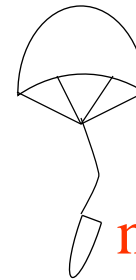
4km (ARLISS)  
altitude



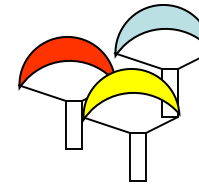
CAN SAT deployment



nosecone

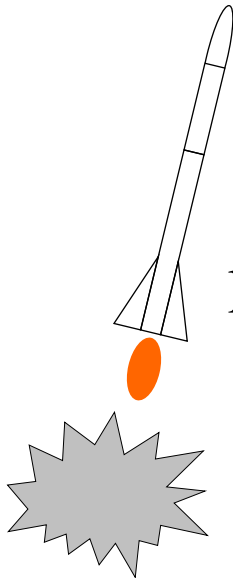


carrier



15-20 min  
after release

launch



# Amateur Rocket Launch and Descent by Parachute

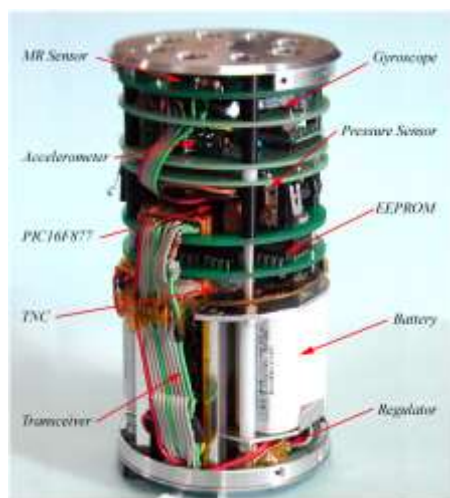
# 1st ARLISS Launch, Sep.1999 Dr. Pius Morozumi's rocket







*Initial Training for  
satellite development  
CanSats 1999 - now*



# ARLISS (A Rocket Launch for International Student Satellites)

## - Annual suborbital launch experiment in USA -

- **ARLISS 1999**: Sept. 11 (Japan:2, USA:2)
  - Univ.of Tokyo, Titech, Arizona State, etc.
- **ARLISS 2000**: July 28-29 (Japan:4, USA:3)
- **ARLISS 2001**: August 24-25 (Japan:5, USA:2)
- **ARLISS 2002**: August 2-3 (Japan:6, USA:3)
- **ARLISS 2003**: Sept.26-27 (Japan:6, USA:3)
- **ARLISS 2004**: Sept.24-25 (Japan:6, USA:3)
- **ARLISS 2005**: Sept.21-23 (Japan:7, USA:3)
- **ARLISS 2006**: Sept.20-22 (Japan:8 USA:3 Europe:1)
- **ARLISS 2007**: Sept.12-15 (Japan:10 USA:3 Korea:1)
- **ARLISS 2008**: Sept.15-20: **10<sup>th</sup> Memorial ARLISS !**

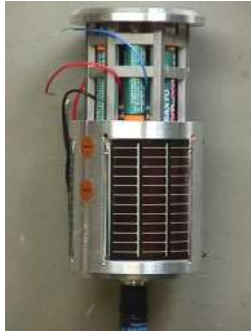


- **ARLISS 2016**: 18<sup>th</sup> (Japan:12, USA:2, Korea, Egypt)
- **ARLISS 2017**: 19<sup>th</sup> Sept.13-17 (Japan:13 USA:2 Kore
- **ARLISS 2018**: **20<sup>th</sup> Memorial !!**

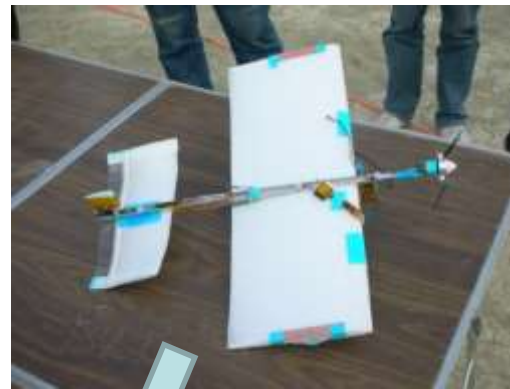




# Variety of CanSat



Nominal 350ml Juice Can size  
(3 CanSats can be launched  
by one ARLISS rocket)



“Open Class”: One CanSat can be  
launched by one ARLISS rocket

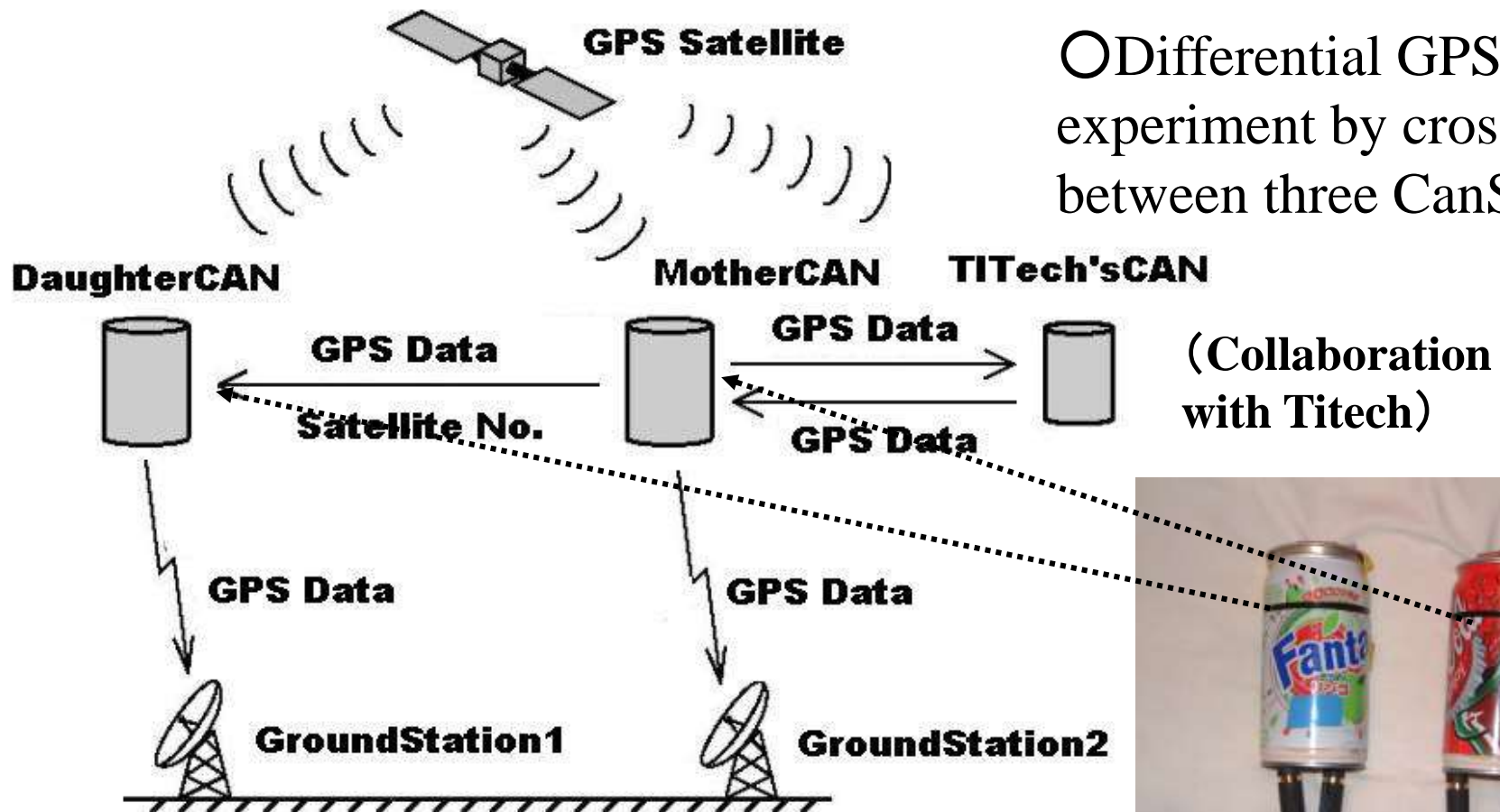


# DGPS Experiment (2000)

## Pre-experiment for future Formation Flying in Space

OGPS measurement and  
downlink

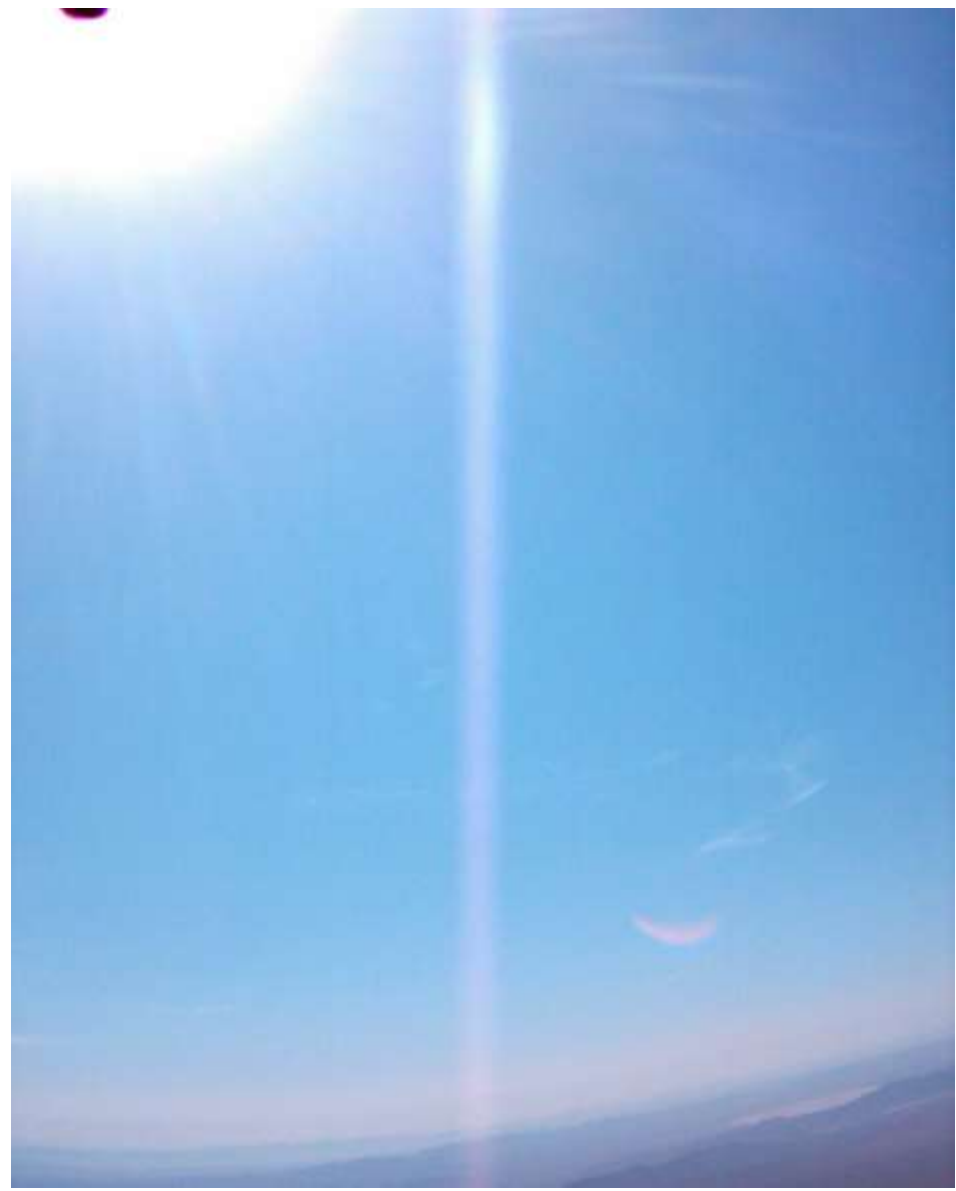
Differential GPS  
experiment by crosslink  
between three CanSats





**Automatic Stand-up  
Experiment (2000)**

# Picture From the Sky



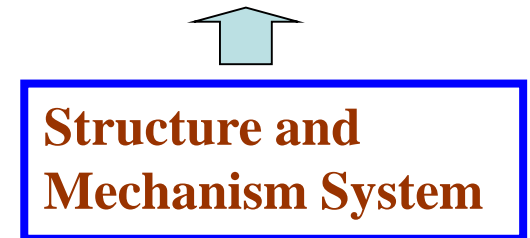
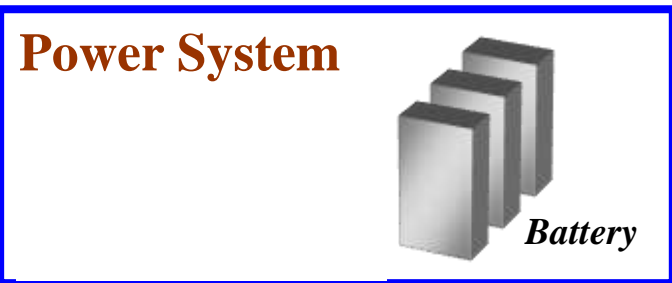
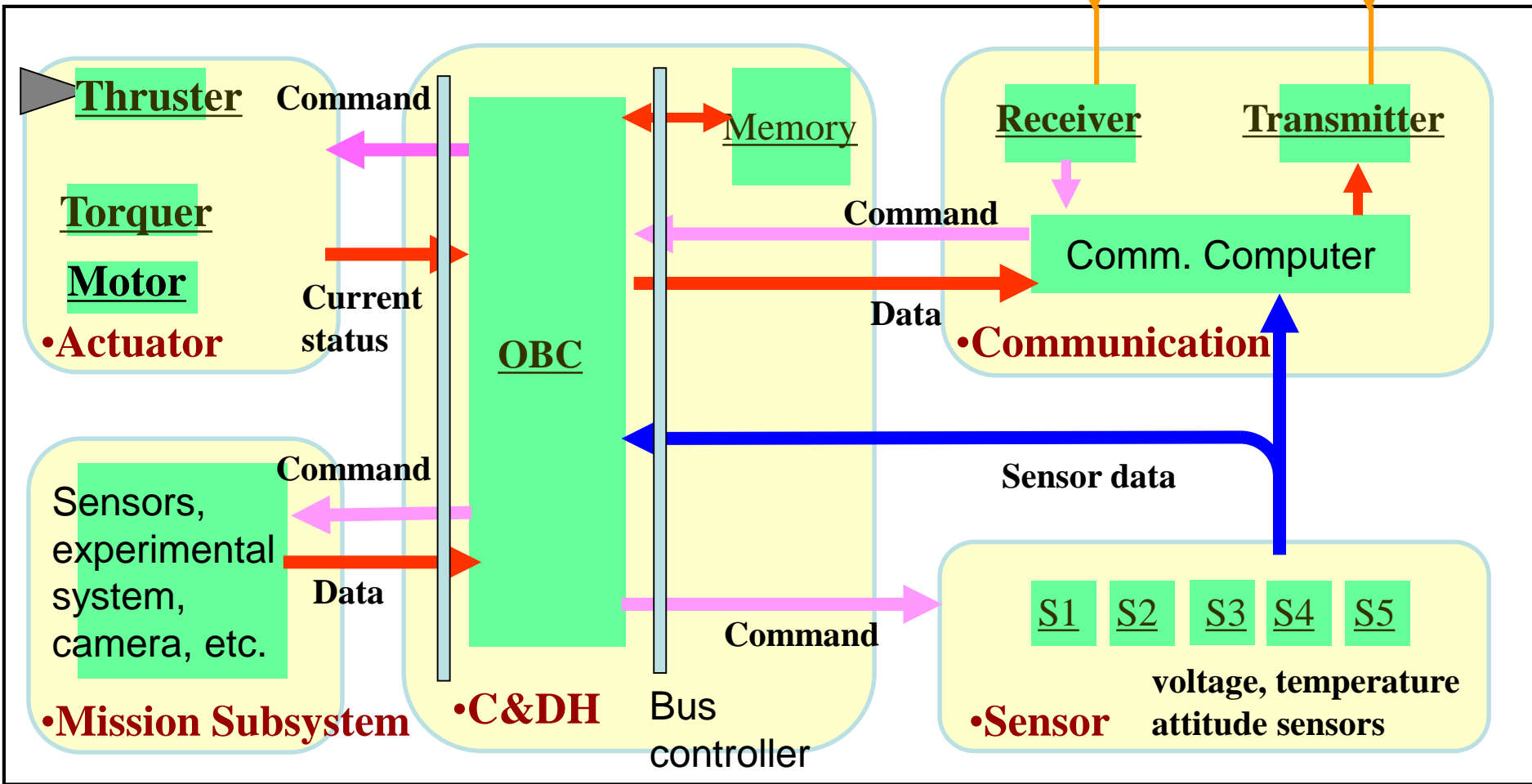


# Significance of CanSat Program

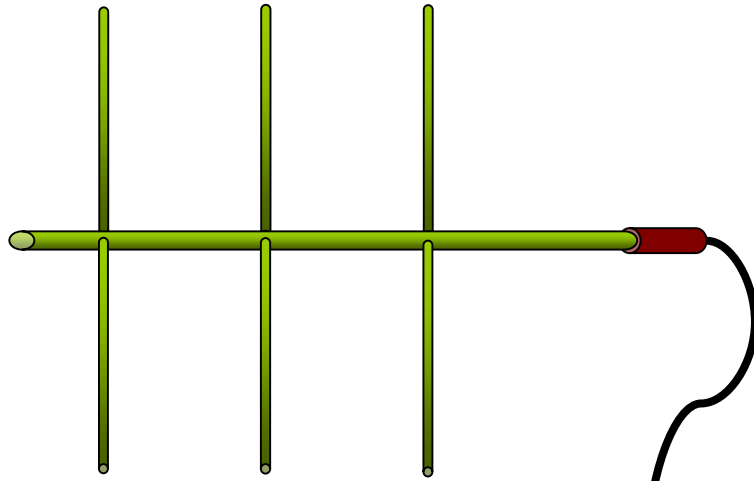
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- **Very Short Period Required for One Whole Project**
  - *5-6 months for mission conceptualization, satellite design, fabrication, ground test, modification, launch, operation*
  - *Launch date is fixed in ARLISS: no delay is allowed*
- **Very Low Life Cycle Cost for One Project**
  - *\$500 - 1,000 budget for one team (typically)*
  - *Helium balloon test requires \$200/day and Rocket launch requires \$400/flight, etc.*
- **Small, but Still Can be “a Satellite”**
  - *All the satellite functions + mission can be packed*
- **Can be Retrieved after Experiment**
  - *Analysis of the causes of failures is easy*
- **Possibility of Sponsorship from Juice or cola company**

# CanSat / Satellite Systems



# Handy Ground Station (for ARLISS Project)



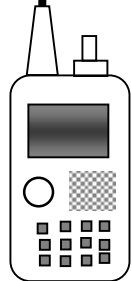
## Yagi-Antenna

- Frequency : 144MHz
- Gain : 8dBi
- length : 87cm
- weight : 530g

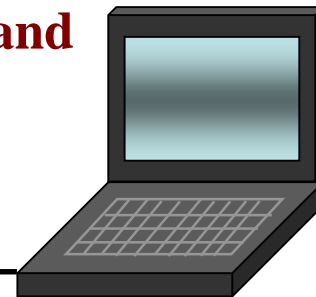
- Reception of downlinked signal, monitor the satellite status, and store the data in computer

## Transceiver

- with TNC
- 144/430MHz dual band
- ☆ TNC
- AX.25
- 1200 / 9600bps

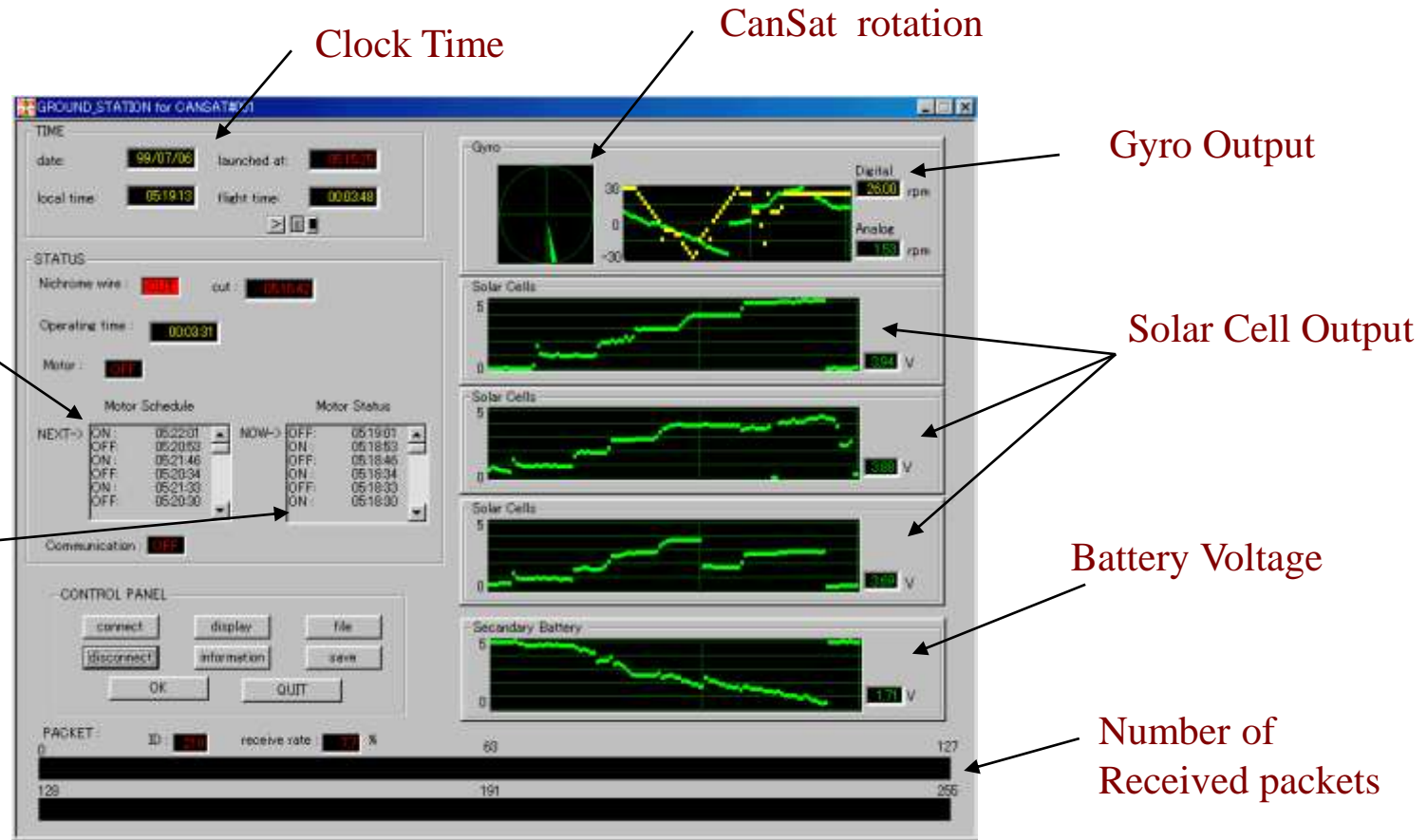


## Note PC





# GS Software on PC (1999)



**Data Logging on Memory.**

# Failure in 2000

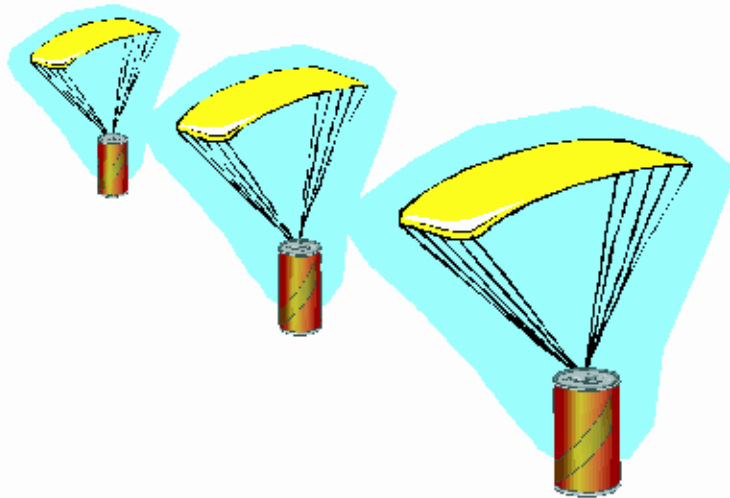
**Parachute and main body were separated and the main body crashed on the ground**



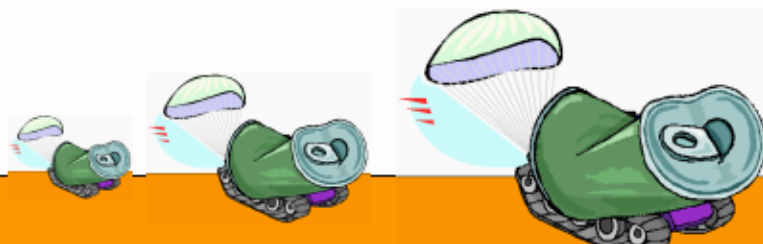
- **Students can learn many things from failures**
- **Engineers should experience failures while the project size is small**

2001年～ Comeback Competition

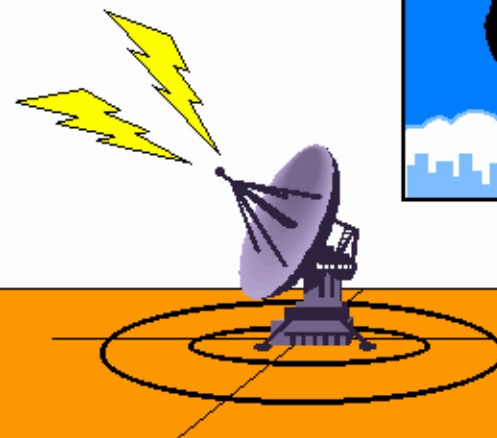
# Competition



***Call Back Your  
CANSAT!!***



**ARLISS2001 PROJECT**





# *Participating Universities 2002*

**Univ. of Tokyo**



**Kyushu Univ.**



**Nihon Univ.**



**Tohoku Univ.**



**Tokyo Institute of Technology**



**Stanford Univ.**

ROVER

**Currently AXELSPACE  
CEO Dr. Yuya Nakamura**

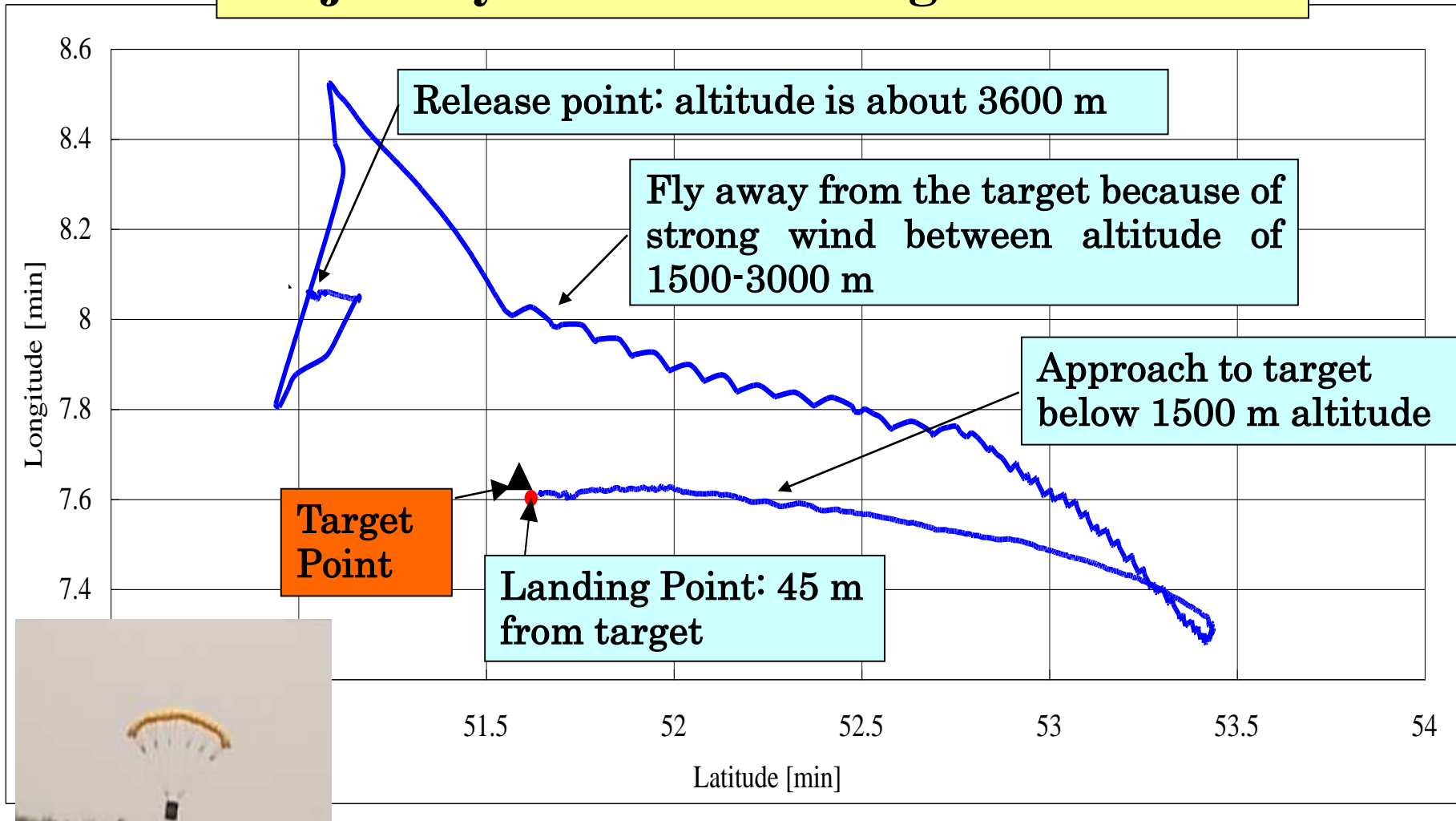
**Target**

**Landed CanSat**

**Flyback Record 45m in 2002**



# Trajectory of 2002 Winning Comebacker



The flyback CanSat was flown by the wind in 1500-3000m altitude, but came back in the lower altitude where the wind became weak.



## Fly-backers



University of Tokyo ISSL



Titech Matunaga Lab B



Kyushu Tech. Cho Lab A

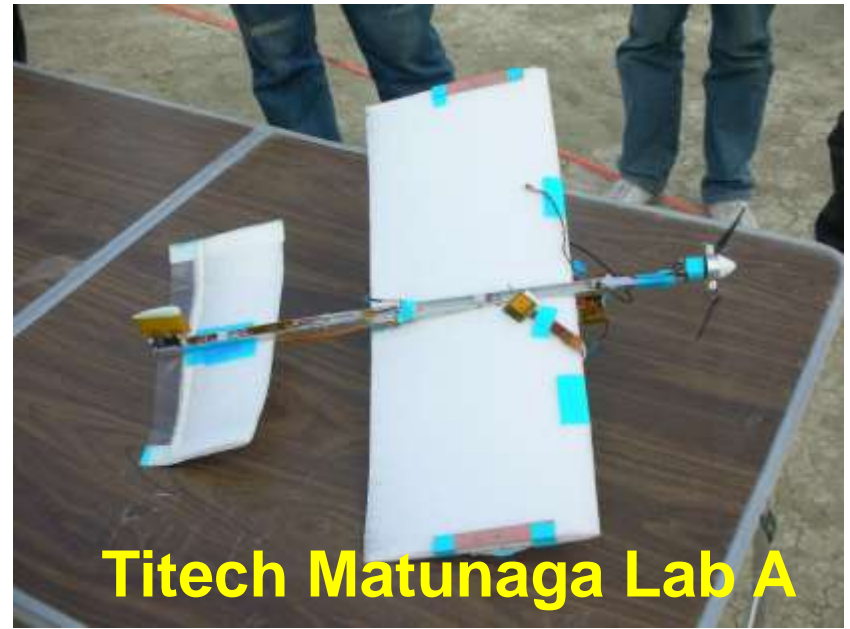


Kyushu Tech. Cho Lab B

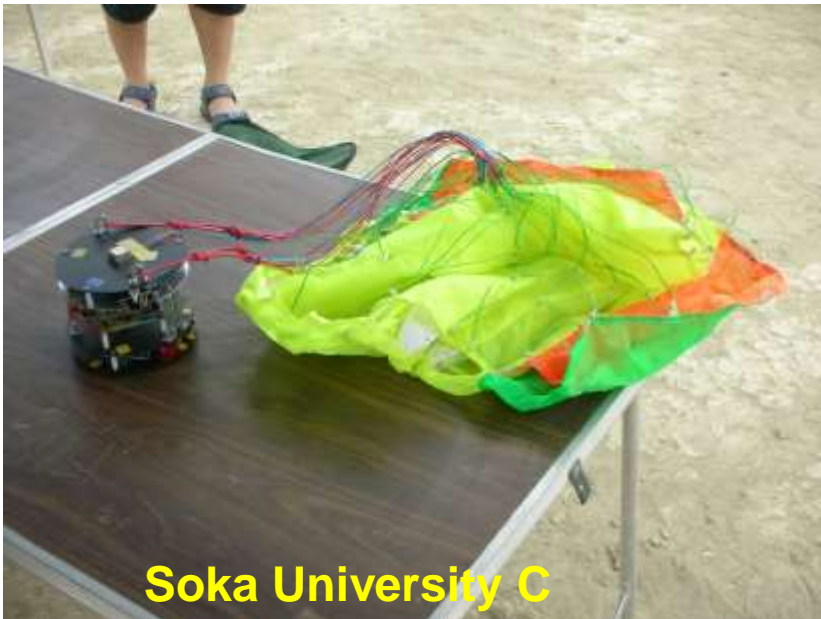
## Fly-backers



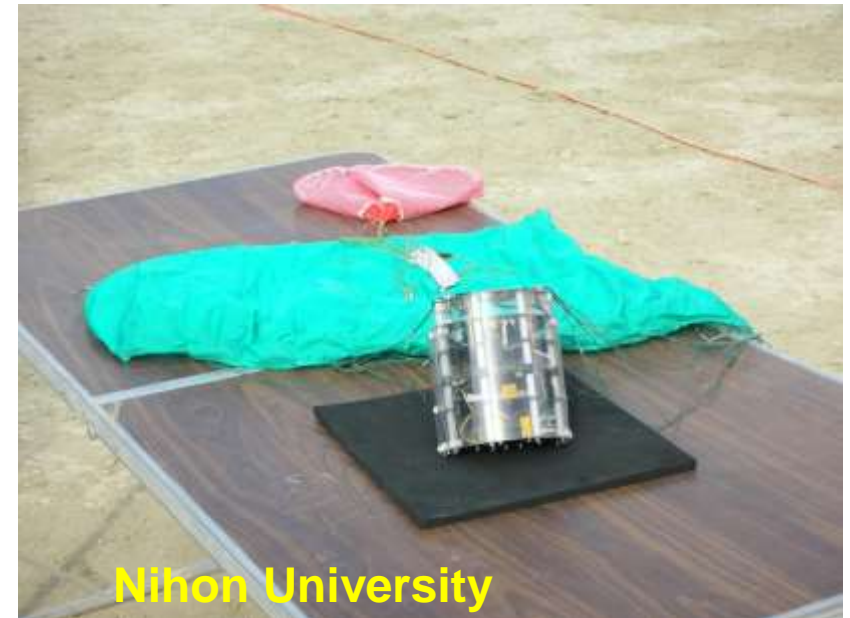
**Akita University**



**Titech Matunaga Lab A**



**Soka University C**



**Nihon University**



# Rovers

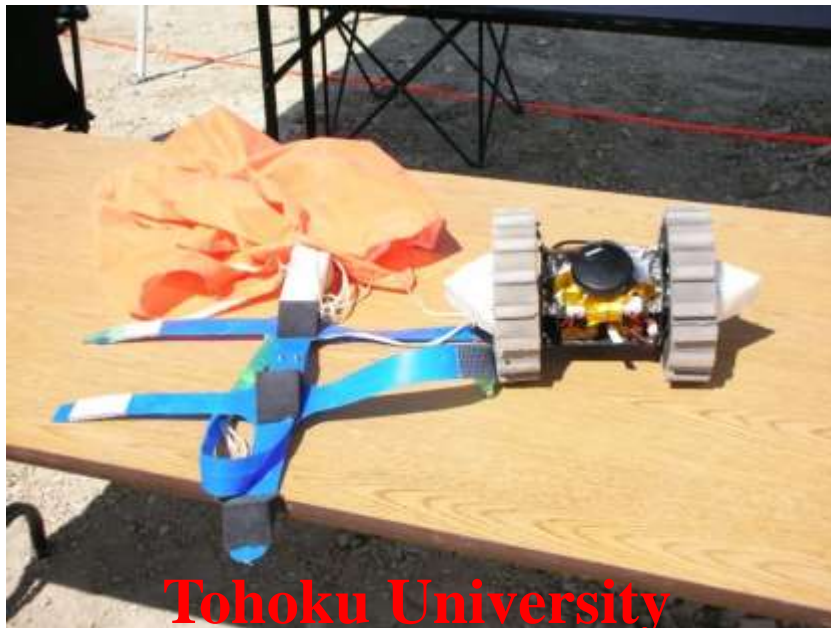
Come-Back Competition 2008



**University of Tokyo B3**



**Tsuyama College**



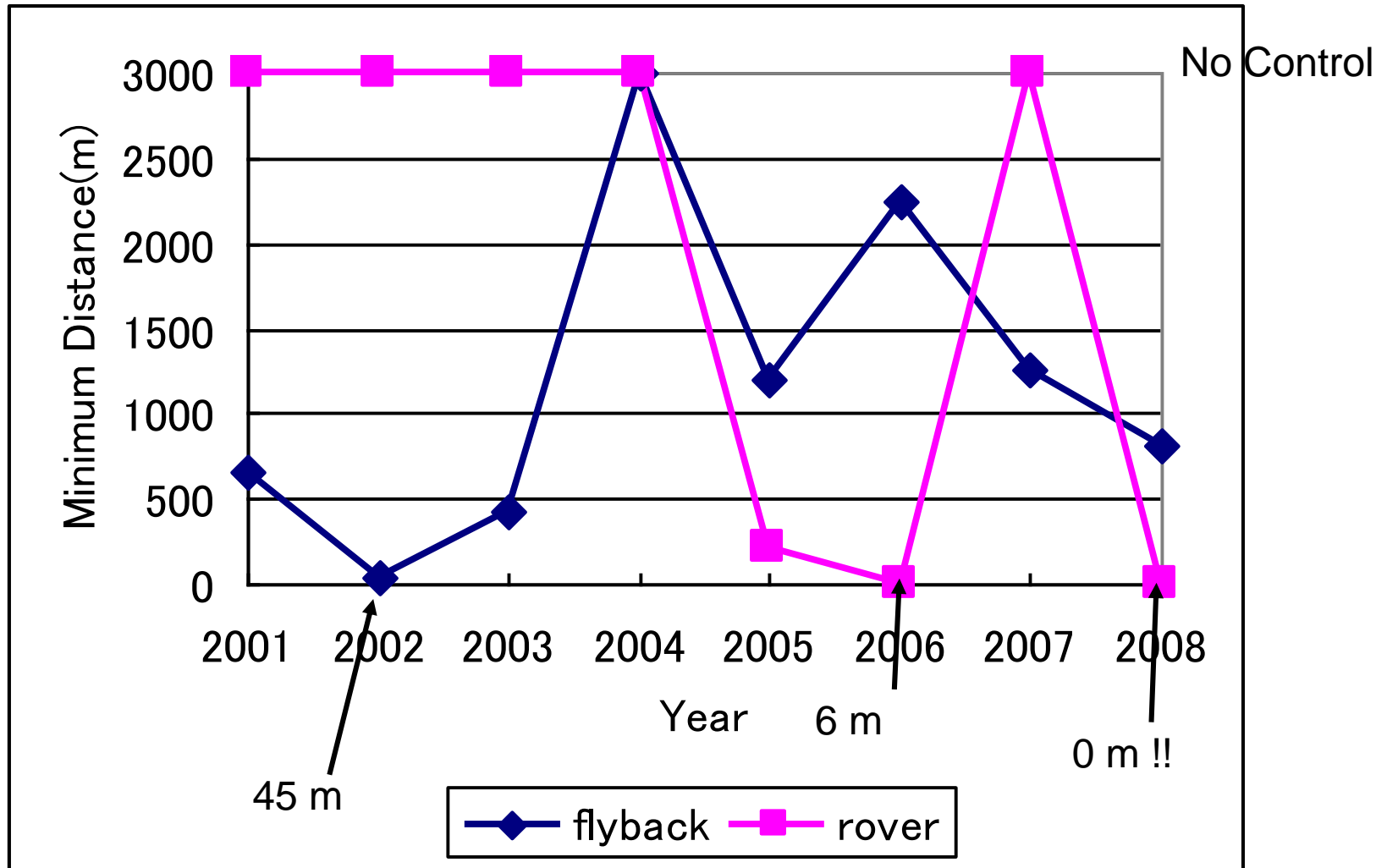
**Tohoku University**



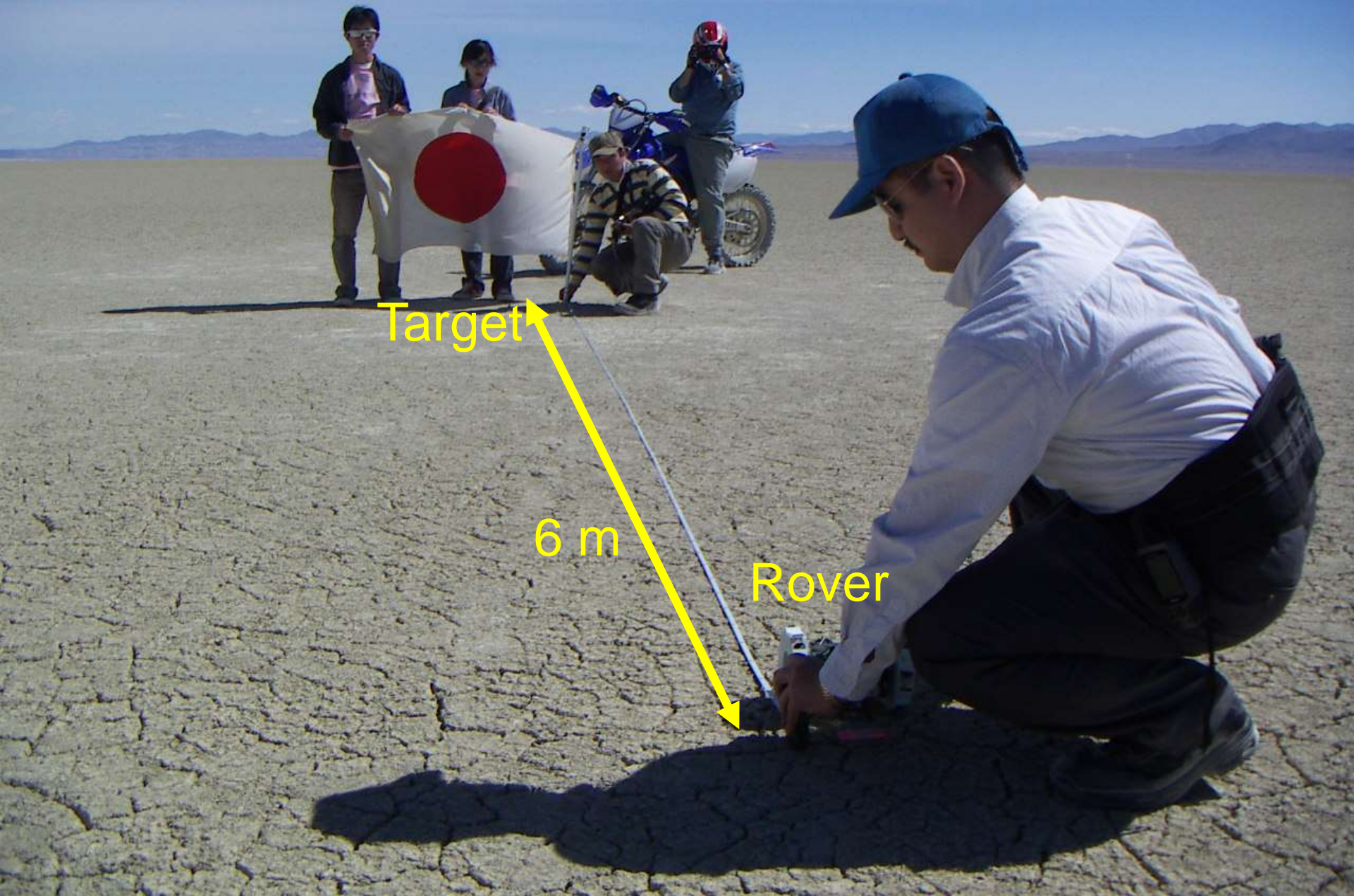
**Univ. for Electro Comm.**



# History of Flyback vs. Rover



In 2006, Tohoku University's Rover made "6 m to the target"



# 2008 Comeback Competition Ranking

**1<sup>st</sup> Place: Tohoku University (R): 0 m**



First 0m achievement

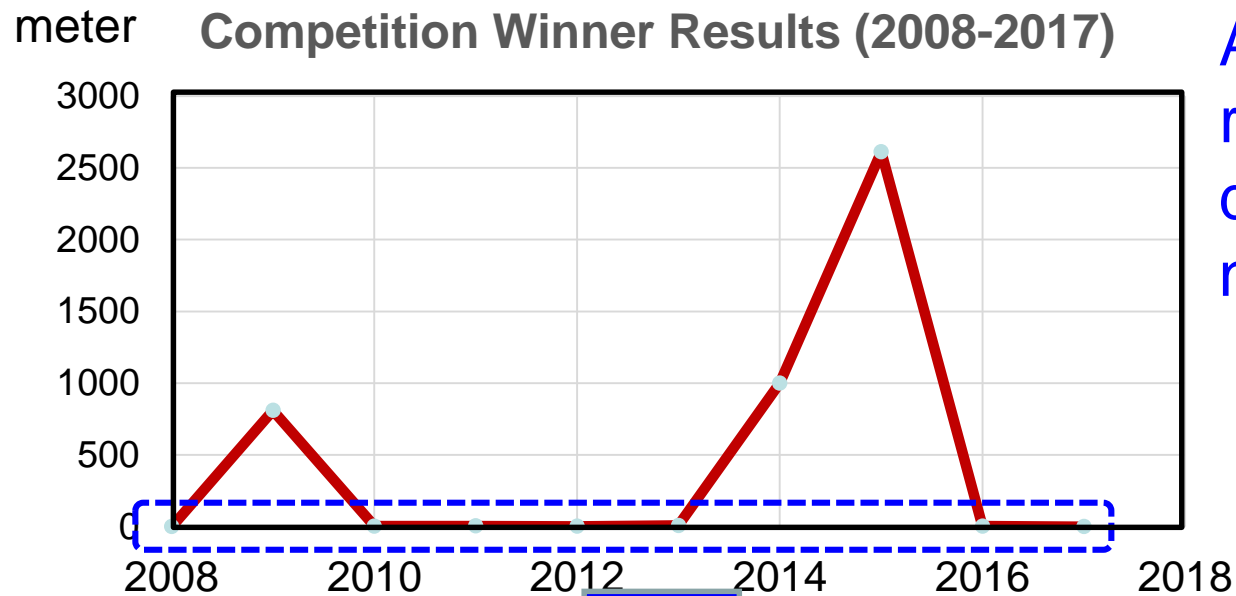
**2<sup>nd</sup> Place: Nihon University (F): 818 m**



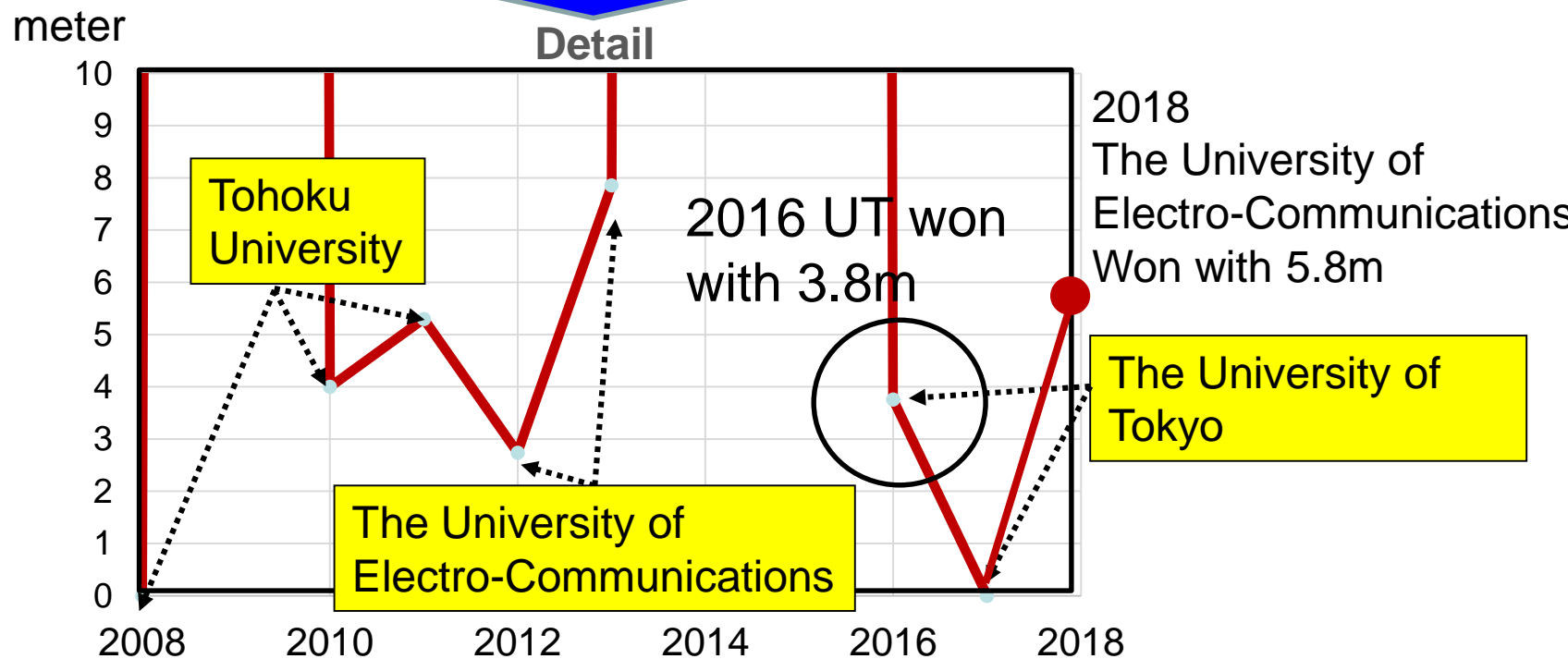
**3<sup>rd</sup> Place: Titech Matunaga Lab (F): 903 m**







After 2008,  
rover has been  
dominating until  
now



# Opening Ceremony and Briefing (September 10, 2018)



# Loading CanSat to Rocket





# Setting Rocket to Launcher



# Launch to 3600m Altitude



# Landing of CanSat





# Pushed away by strong wind



How about making this a speed contest ?



Envelope opened and escaped,  
but....





In the Second Run, they achieved 3.8m to the target and won !





In 2017, University of Tokyo team approached 1.34m to the target, when it automatically started image navigation. But because of bad direction of sun light, it gave up.



After modification of software, it achieved 0m to the target in the second run !

2<sup>nd</sup> 0 m Achievement



Presented as a Gift to AEROPAC in 2018



# 2018, Students Challenge “Flyback”



Result was 900m and was awarded Best Comeback Technology Award



# Breakfast Meeting on Final Day

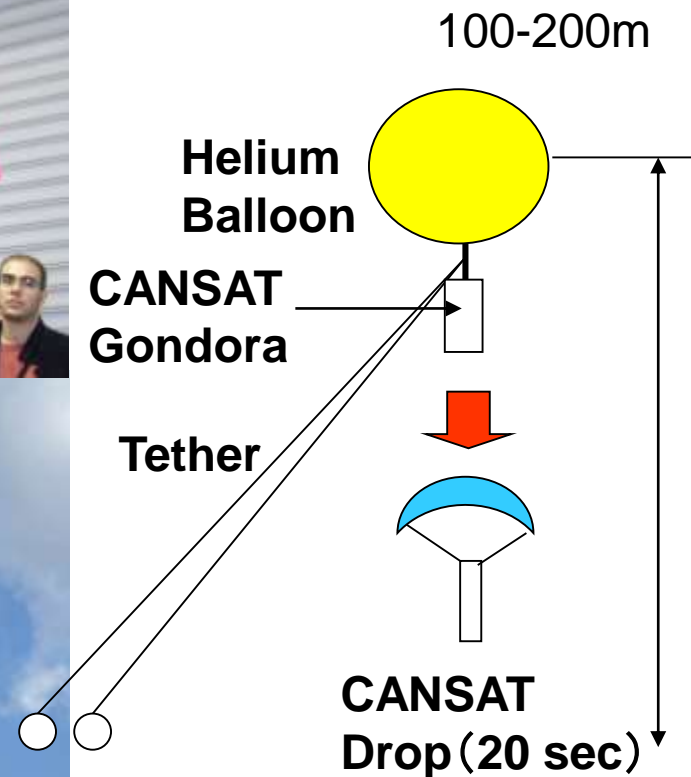


# 20<sup>th</sup> Anniversary Gifts to AEROPAC (Sept 14, 2018)



# Balloon Experiment in Japan

- Itakura Competition 2002 (Thermal balloon)
- Noshiro Space Event 2005~
- IAC Fukuoka International Competition 2005





# CanSat Workshop (2007.2)

- 16 Countries
- Contest started in Europe (Spain, Norway---)
- Strong desire for educational support from Japan to emerging countries



# CLTP (CanSat Leaders Training Program) History

64+ participants  
from 32+ countries

## CLTP1 (Wakayama Univ. in Feb-March, 2011)

12 from 10 countries, namely Algeria, Australia, Egypt, Guatemala, Mexico, Nigeria, Peru, Sri Lanka, Turkey (3), Vietnam.

## CLTP2 (Nihon Univ. in Nov-Dec, 2011)

10 from 10 countries, namely Indonesia, Malaysia, Nigeria, Vietnam, Ghana, Peru, Singapore, Mongolia, Thailand, Turkey.

## CLTP3 (Tokyo Metropolitan Univ. in July-August, 2012)

10 from 9 countries, namely Egypt (2), Nigeria, Namibia, Turkey, Lithuania, Mongolia, Israel, Philippines, Brazil.

## CLTP4 (Keio Univ. in July-August, 2013)

9 from 6 countries, namely Mexico(4), Angola, Mongolia, Philippines, Bangladesh, Japan.

## CLTP5 (Hokkaido Univ. in Sept 8-19, 2014)

7 from 5 countries, namely Korea (2), Peru, Mongolia, Mexico (2), Egypt.

## CLTP6 (Hokkaido Univ. in August 24-Sept 3, 2015)

8 from 8 countries, namely Bangladesh, Egypt, Mexico, New Zealand, Angola, Turkey, Tunisia, Austria

## CLTP7 (Hokkaido Univ. in Sept 21-Oct 1, 2016)

8 from 7 countries, namely Egypt, Peru, Mongolia, Nepal, Myanmar, Serbia, Dominica Republic

## CLTP8 (Nihon Univ. in Sept 7-16, 2017)

## CLTP9 (Nihon Univ. in Aug 20-31, 2018)



HeptaSat

# What CanSat Contributed ?

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- Even in small scale, the following important technologies and skills were learnt:
  - System analysis and design
  - Project management and team work
  - How to avoid failures and make recoveries
- We should develop from parts, not by buying components, by which we could learn:
  - How to make components from parts or by modifying the COTS components
- Systems usually do not work as expected. Many many test/refine process required.



# Continued to Real Orbital Project - CubeSat -



# USSS has been held annually in many islands under JUSTSAP

1998 Oahu CanSat proposed

1999 Kauai CubeSat proposed

2000 Big Island, Hiro

2001 Big Island, Kona

2002 Oahu

2003 Oahu

2004 Oahu

2005 Oahu

by Prof. Twiggs again



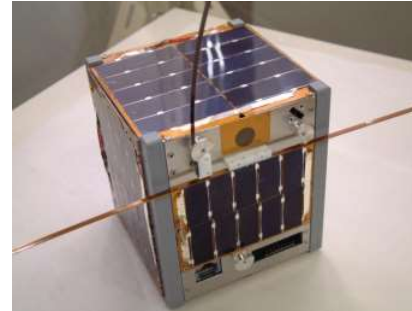


# Emergence of Nano/pico-Satellites in Japan

## World First CubeSats launch by Univ.Tokyo and Titech (2003.6.30)

- University level budget (30K\$)
- Development within 2 years
- Surviving in space for >15 years
- Ground operations, frequency acquisitions, launch opportunity search processed by ourselves

Many Japanese universities start developing their own satellites through UNISEC network



**CubeSat XI-IV & CUTE-1**



**Russian Launch**





# UNISEC started during CubeSat development (UNiversity Space Engineering Consortium)

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- Founded in 2002 (5 universities), became NPO in 2003
- In 2017, 72 laboratories from 50 universities
  - 892 students, 259 individual/company members
- **UNISEC Missions:**
  - Education and human resource training for space development/utilization
  - Innovative space technology “seeds” development
- **Activities to be Supported:**
  - Joint experiment, joint purchase of parts/ground tests, etc.
  - Workshop, symposium, technology exchange, etc.
  - Consultation on legal matters (frequency, export law, etc.)
  - Finding “rivals” within the community !
  - “UNISEC Lecture Series”



**<http://www.unisec.jp>**

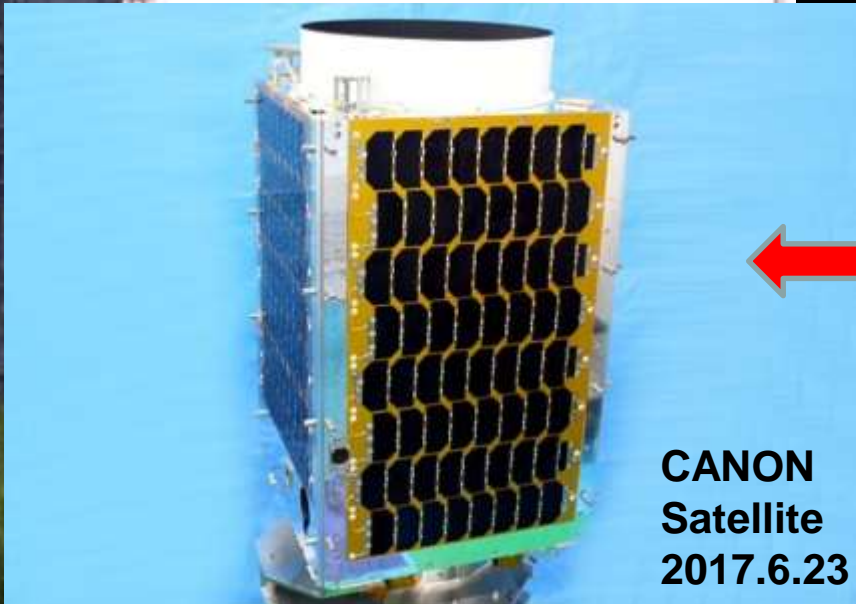
# Launch of the World First CubeSat (XI-IV, CUTE-1) by “ROCKOT”

2003/06/30 18:15:26 (Ru

Contribution to human  
resource training was  
more than expected !



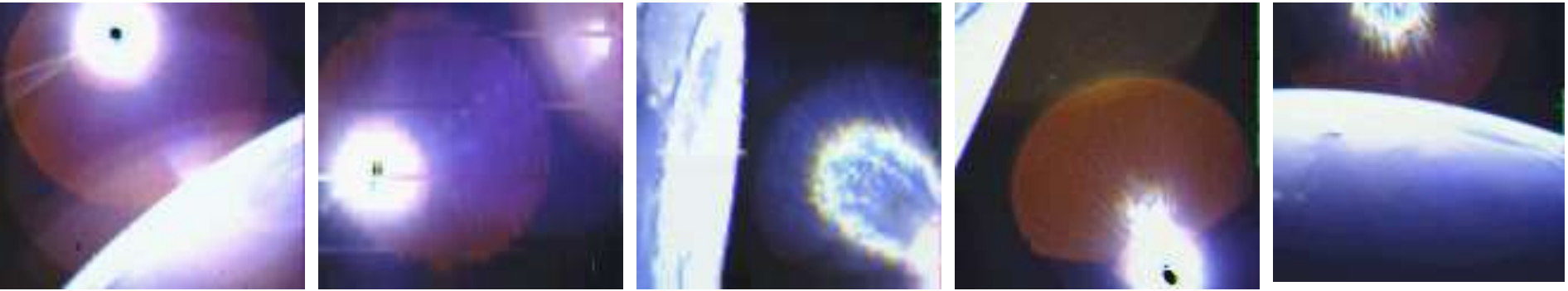
Hayabusa-2



CANON  
Satellite  
2017.6.23



700+ pictures downlinked for 15+ years

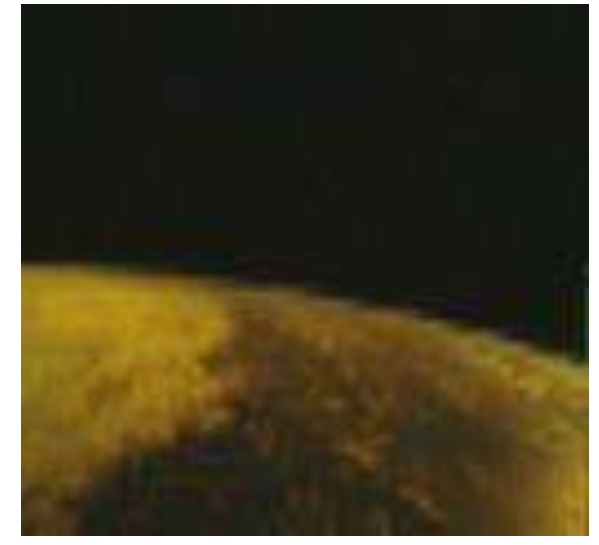
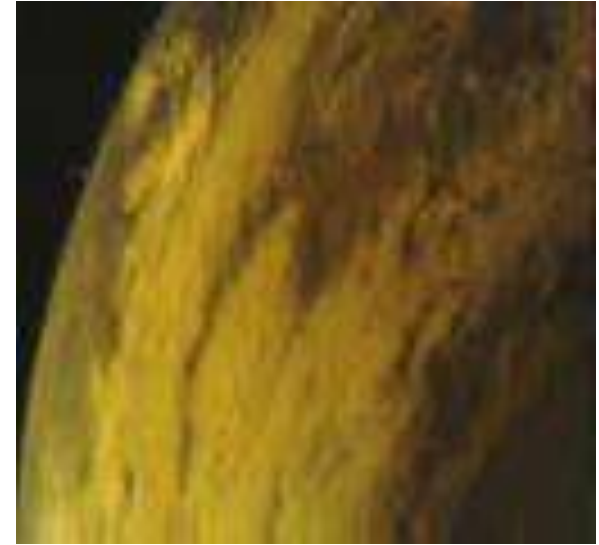
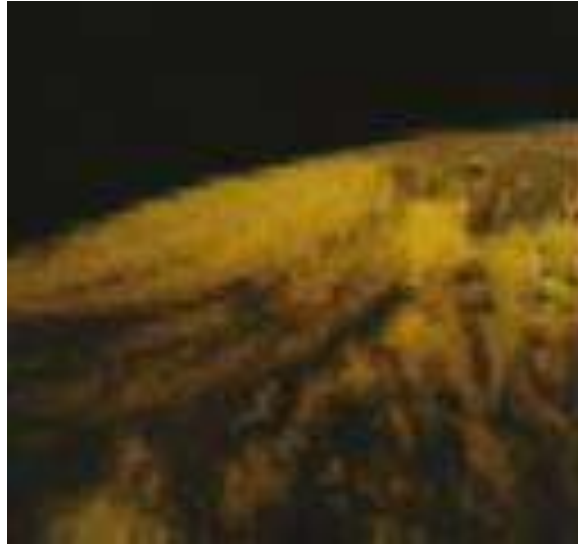
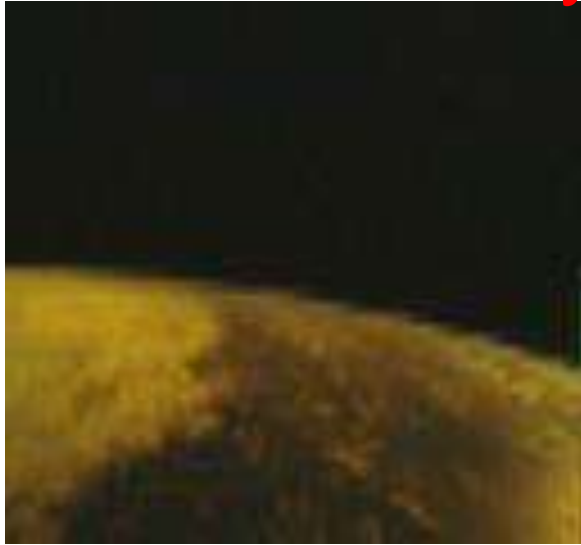




XI-IV is still perfectly working  
after 15 years in orbit

Recently Downlinked Photos

*Sepia color !  
Get older ?*



# Key strategy to be world first CubeSat

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- No components on web-site for CubeSat
  - Everything should be internally-made
- No ground test facilities in our university
- We only have little money (\$55,000)
- Key strategies employed in our first CubeSat
  - Find out and pursue **what we can do within our limited resources, not aiming at supreme level**
  - Find **outside supporters** (technical, part donation)
  - Make it as simple as possible (**start from very very simple CubeSat**)
  - Implement **survivability** as much as possible

## Power-system

PWR5V

# Satellite's Key Technological Issue

## “non-repairable system”

*How to realize a certain level of reliability within limited resources (size, weight, power) ??*

OBC

TX-DCDC

OBC

CWRX-system

CMD

RX TNC

RX

CW

log SW

## “Die Hard” system is essential !!

- Mutual monitoring or hierarchical monitoring
- “Reset (power off-on)” operation
- Solar power generation possible in any attitude
- Under voltage control (UVC) and recovery from dead battery situation
- Appropriate definition of “safe mode”

Solar Cell

Battery

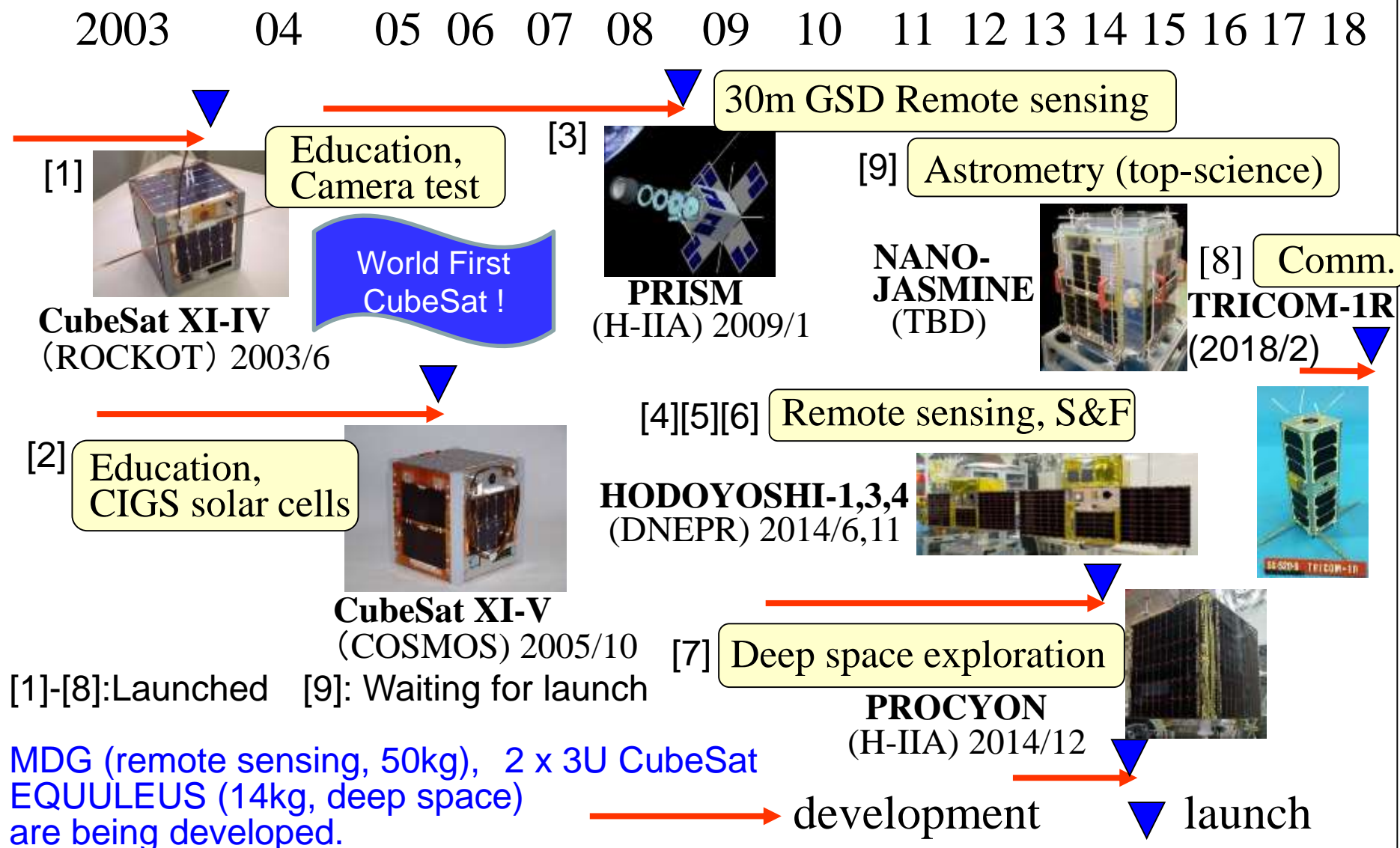
alog

Analog Sensors



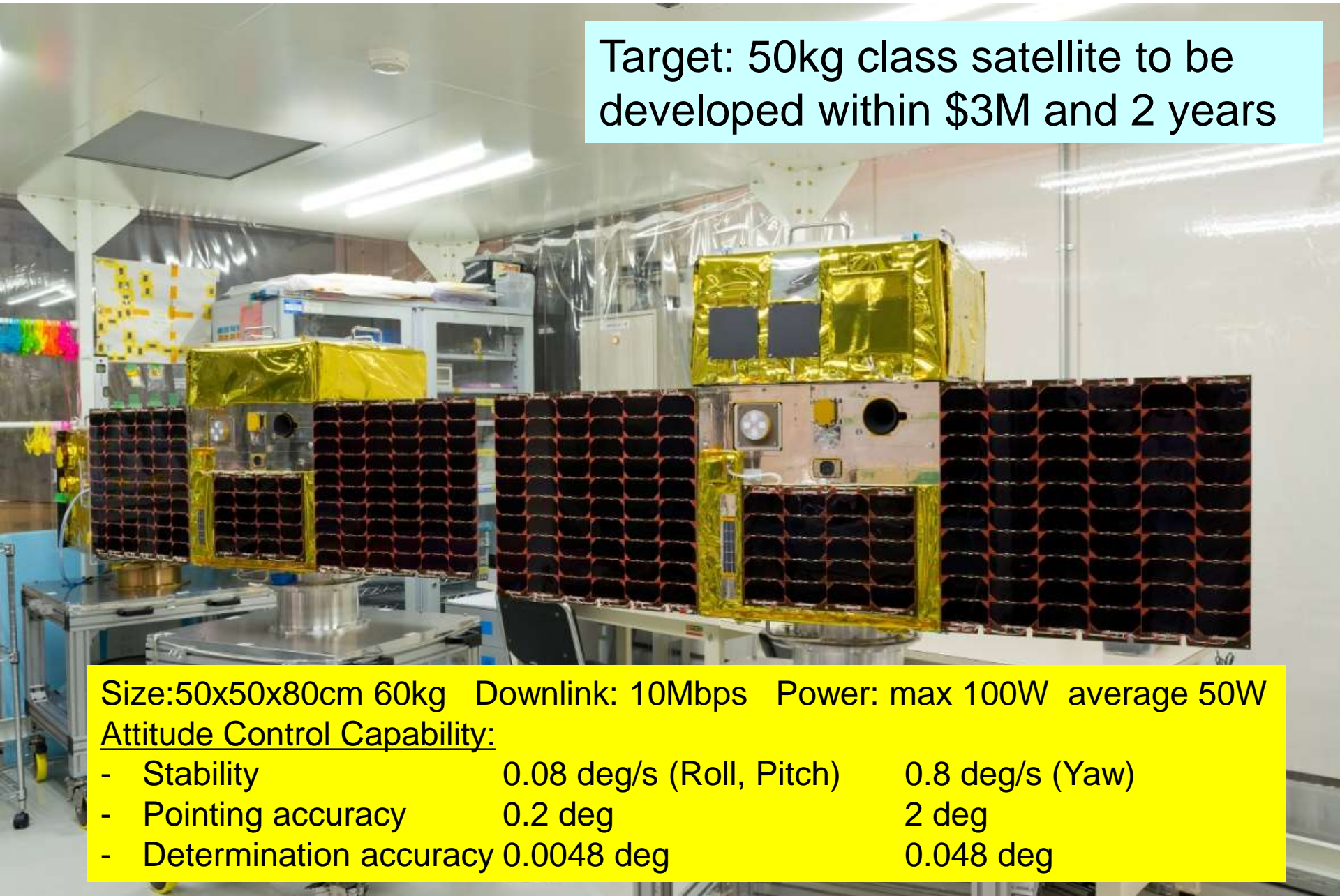
# University of Tokyo's History

## - 9 satellites developed (8 launched) -



# Hodoyoshi-3 (left) and Hodoyoshi-4 before Shipment (April, 2014)

Target: 50kg class satellite to be developed within \$3M and 2 years



Size: 50x50x80cm 60kg Downlink: 10Mbps Power: max 100W average 50W

## Attitude Control Capability:

- |                          |                          |                 |
|--------------------------|--------------------------|-----------------|
| - Stability              | 0.08 deg/s (Roll, Pitch) | 0.8 deg/s (Yaw) |
| - Pointing accuracy      | 0.2 deg                  | 2 deg           |
| - Determination accuracy | 0.0048 deg               | 0.048 deg       |

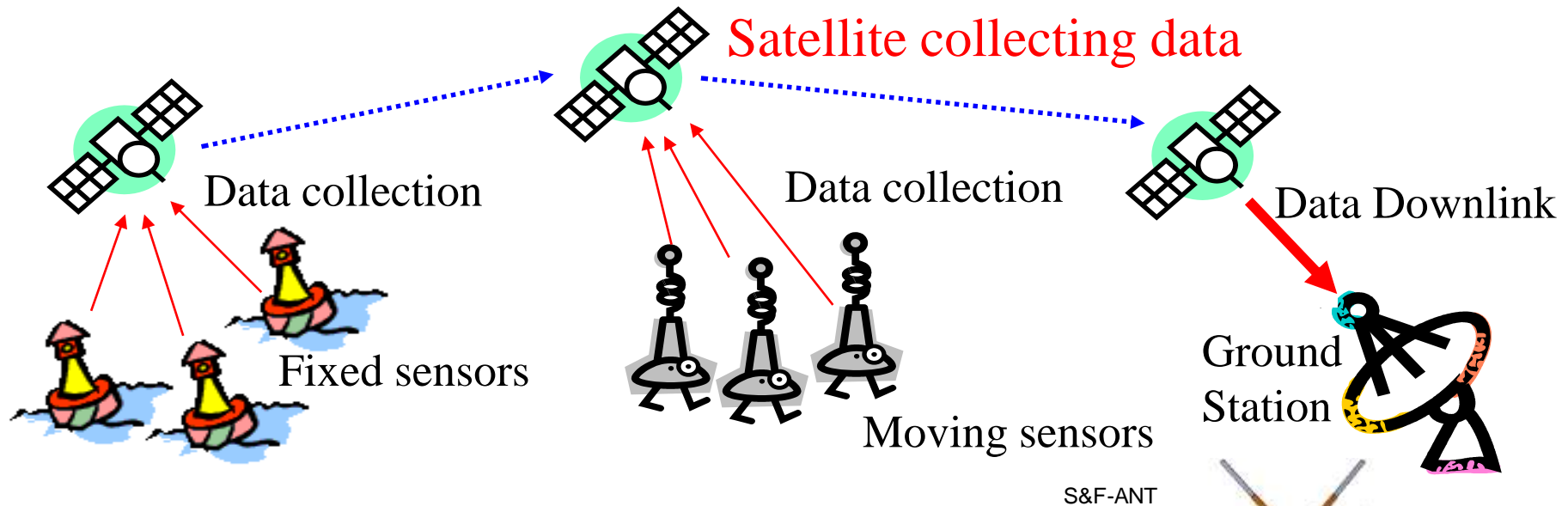




Chiba  
(6m GSD)



# “Store & Forward” collects ground information

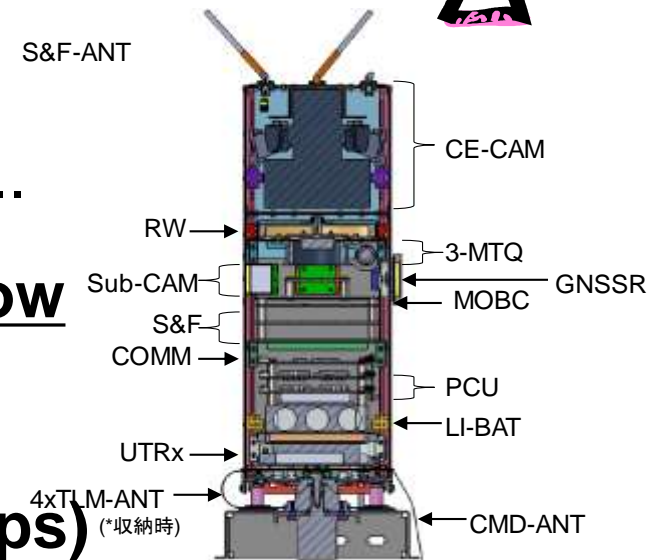


Application areas: disaster prediction,  
water level monitoring, soil moisture, PH.....

Key Issue: How to send data with very low  
RF power to the satellite ?



**8mW low RF power, low data rate (300bps)  
transmission is tested in TRICOM-1R.**



**3kg TRICOM-1R**

# Launch of TRICOM-1R by SS-520-5

- Launched on **3/2/2018** by the world smallest orbital rocket by JAXA/ISAS
- S&F and camera experiments successful
  - 8mW transmission from Japan, RWANDA, etc
- Plan to develop **low cost/quick development version to support foreign countries**





**MOU to develop 3U CubeSat to be launched in mid 2019**

**News from Africa (09/05/2018)**

**Smart Africa, Rwanda Sign Deal With Tokyo University For Satellite Technology**

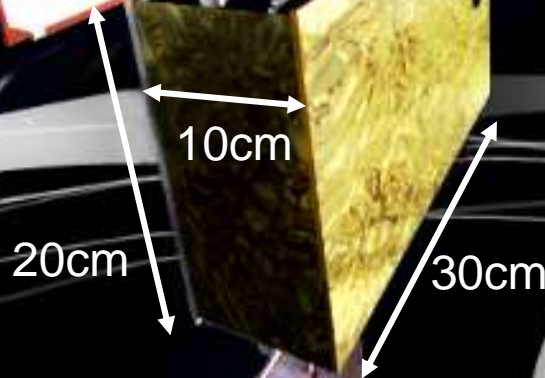




# EQUULEUS

One of 13 EM-1 CubeSats  
onboard NASA's SLS-rocket

EQUilibriUm Lunar-Earth point 6U Spacecraft (6U)



Mission to Earth Moon Lagrange Point

Intelligent Space Systems Laboratory, 2016/08/01

# 6U CubeSat size “EQUULEUS”

Solar Array  
Paddles  
with gimbal

Ultra-stable Oscillator

Propellant (water) Tank

Transponder

X-Band MGA

X-Band LGA

20cm

Battery

CDH &  
EPS

X-Band LGA

Water resistojet  
thrusters

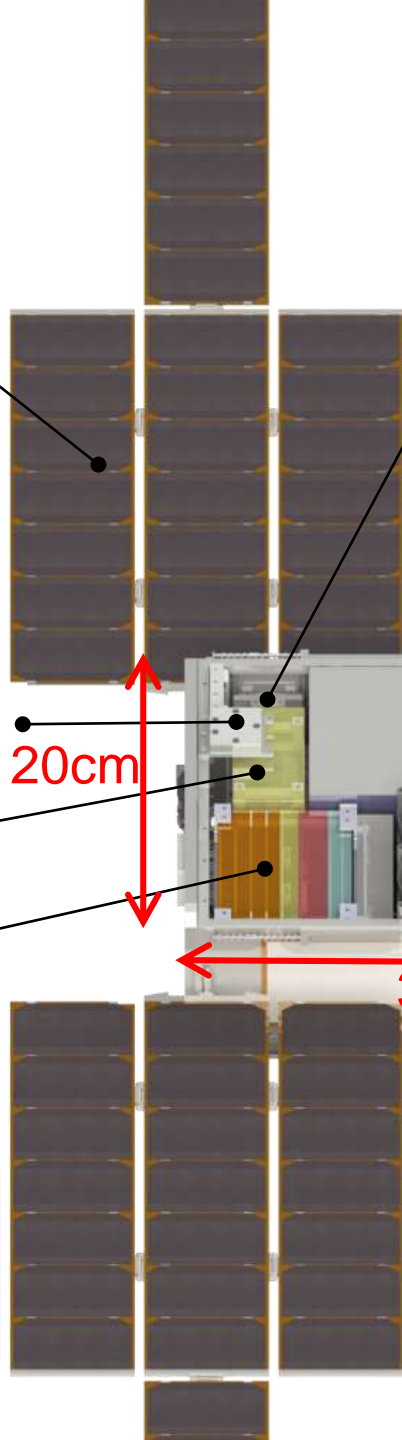
Attitude control unit

30cm

PHOENIX (plasma-sphere  
observation)

DELPHINUS (lunar impact flashes  
observation)

Condensed  
14kg !!



# University Satellites in Japan

## 48 university satellites launched in 2003-2017



From CanSat to CubeSat, Nano-Satellite  
From Educational purpose to Practical application



# Japanese University Satellite Launch (2003-2017)

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- Foreign Rockets: 12

– ROCKOT (Russia)	2	(2003)
– COSMOS (Russia)	1	(2005)
– PSLV (India)	3	(2008, 2012)
– DNEPR (Russia)	6	(2014)

- Japanese Rockets and ISS: 36

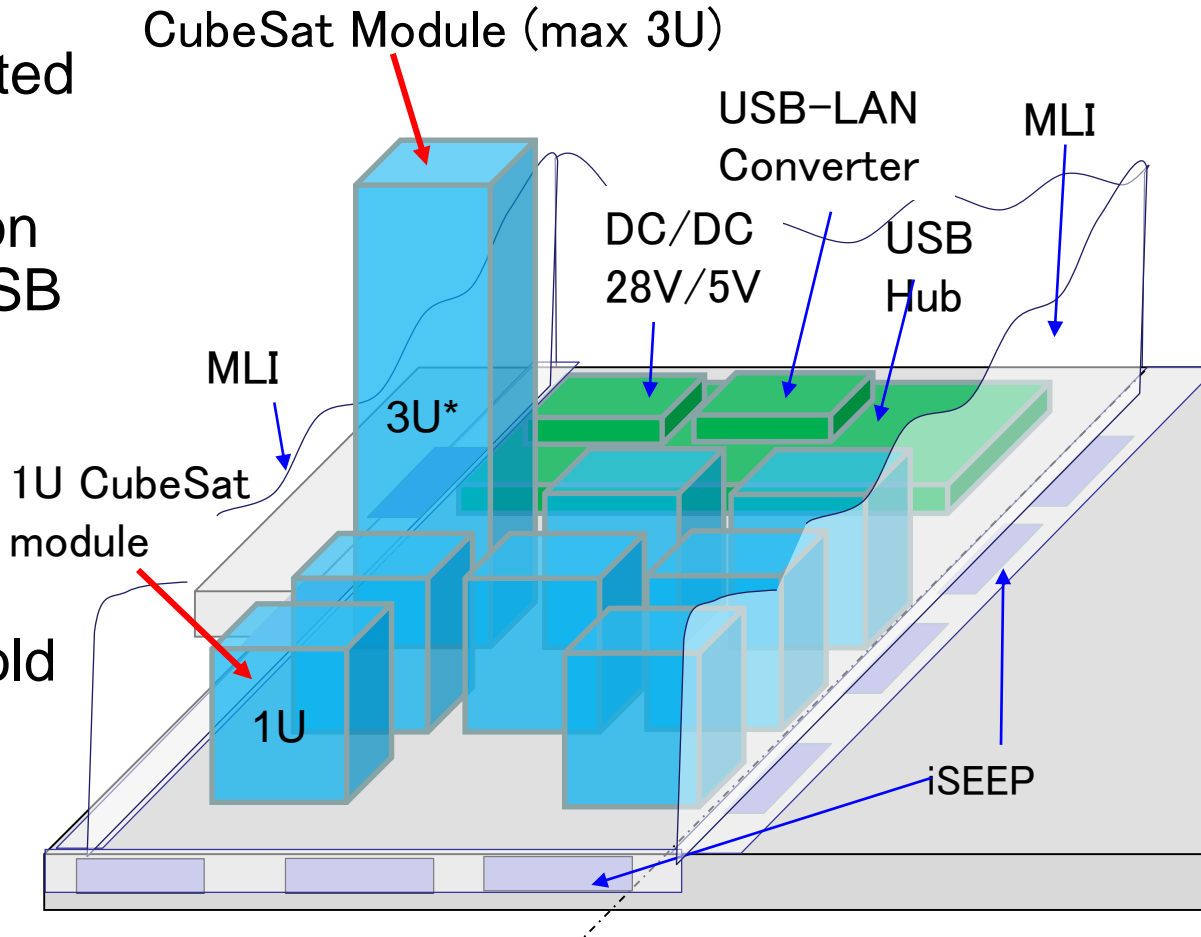
– M-V	2	(2006)
– H-IIA	19	(2009~)
– HTV⇒ISS deployment	15	(2012~)

JAXA supported University satellite projects !

# Attaching CubeSat to ISS (on “i-SEEP” )

*Coming soon !!*  
*Check JAXA website.*

- CubeSat module:  
100W×100L×113.5H  
3U is acceptable
- 8 Units can be implemented  
on one side of i-SEEP
- Power and communication  
service is provided via USB
  - Power: 5V 4W
  - Comm.: 100kbps  
(Ethernet)
- Thermal: connected to cold  
plate. Total system is  
covered by MLI
- Each CubeSat module is  
launched separately and  
attached to i-SEEP by crew



Note) These parameters are tentative ones.

# Summary and Proposal in UNIGLO

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- We followed reasonable steps;
  - Satellite design contest to learn system design
  - CanSats to learn basic satellite-like development
  - CubeSat to learn simple yet real space system development
  - More sophisticated satellites for practical applications
- Making components from basic parts would be difficult, but eventually it will contribute to the growth of our technologies and skills
- Keep UNISEC-mind: strong will, never-give-up mind, rivalry feeling, honest as to engineering--